



<https://hao-ai-lab.github.io/dsc291-s24/>

DSC 291: ML Systems Spring 2024

LLMs

Parallelization

Single-device Optimization

Basics

Logistics

- Please start preparing your final project talk
 - We will use week 10 (may need additional time) to go through each team's talk
 - The talk orders have been out
 - Please upload your slides to TAs by next Tuesday
 - TAs has distributed some rubrics/guidelines

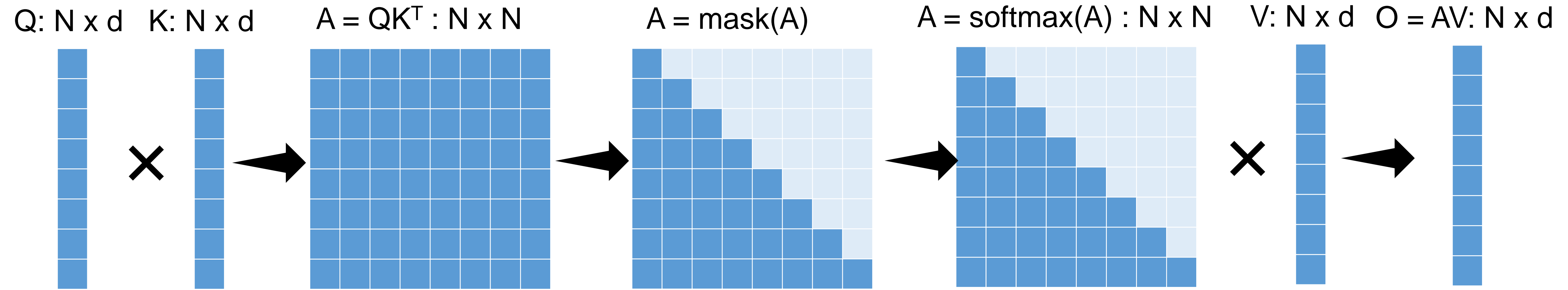
Course Evaluation

- Course evaluation is sent out
 - May 27 at 12:00 AM and Saturday, June 8
- Please fill the course evaluation
 - It is important for you:
 - Get your 2% if 80% of you filled the survey
 - It is important for TAs!
 - It is important for me!

Where We Are: LLMs

- Transformers and Attentions
- LLM Training Optimizations
 - **Flash attention**
 - 3D parallelism
- LLM Inference and Serving
 - Paged attention
 - Continuous batching
 - Speculative decoding
- Scaling Laws
- Long context

Attention: $O = \text{Softmax}(QK^T) V$



Attention Computation

Algorithm 0 Standard Attention Implementation

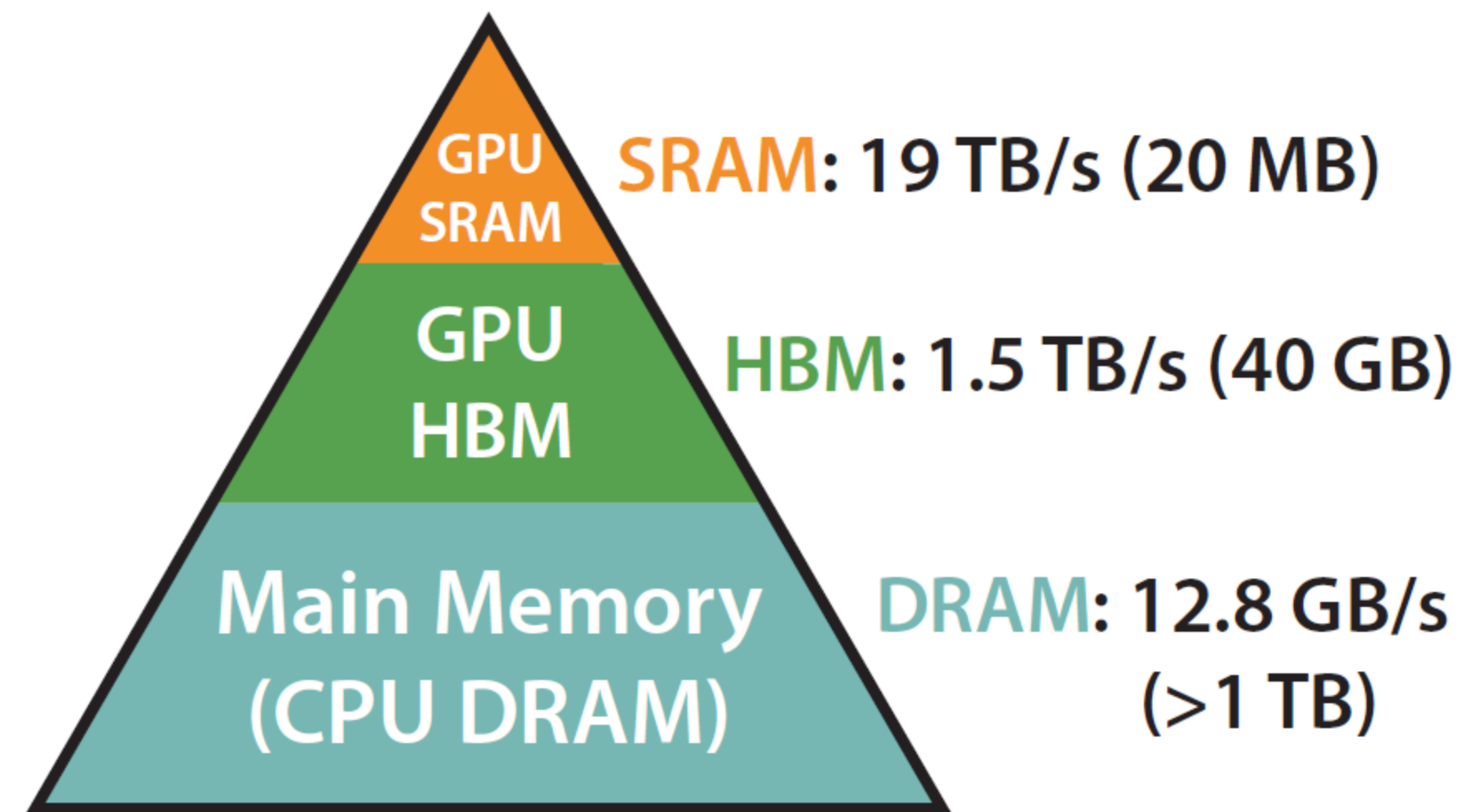
Require: Matrices $\mathbf{Q}, \mathbf{K}, \mathbf{V} \in \mathbb{R}^{N \times d}$ in HBM.

- 1: Load \mathbf{Q}, \mathbf{K} by blocks from HBM, compute $\mathbf{S} = \mathbf{QK}^\top$, write \mathbf{S} to HBM.
 - 2: Read \mathbf{S} from HBM, compute $\mathbf{P} = \text{softmax}(\mathbf{S})$, write \mathbf{P} to HBM.
 - 3: Load \mathbf{P} and \mathbf{V} by blocks from HBM, compute $\mathbf{O} = \mathbf{PV}$, write \mathbf{O} to HBM.
 - 4: Return \mathbf{O} .
-

Challenges:

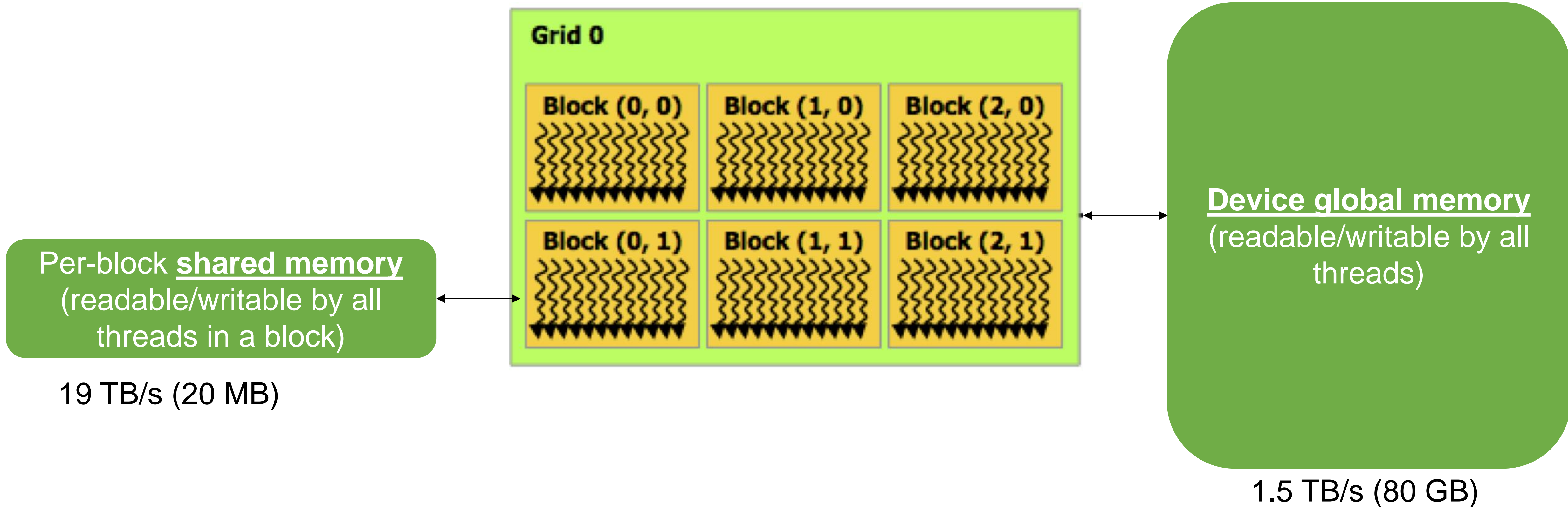
- Large intermediate results
- Repeated reads/writes from GPU device memory
- Cannot scale to long sequences due to $O(N^2)$ intermediate results

Revisit: GPU Memory Hierarchy



Memory Hierarchy with
Bandwidth & Memory Size

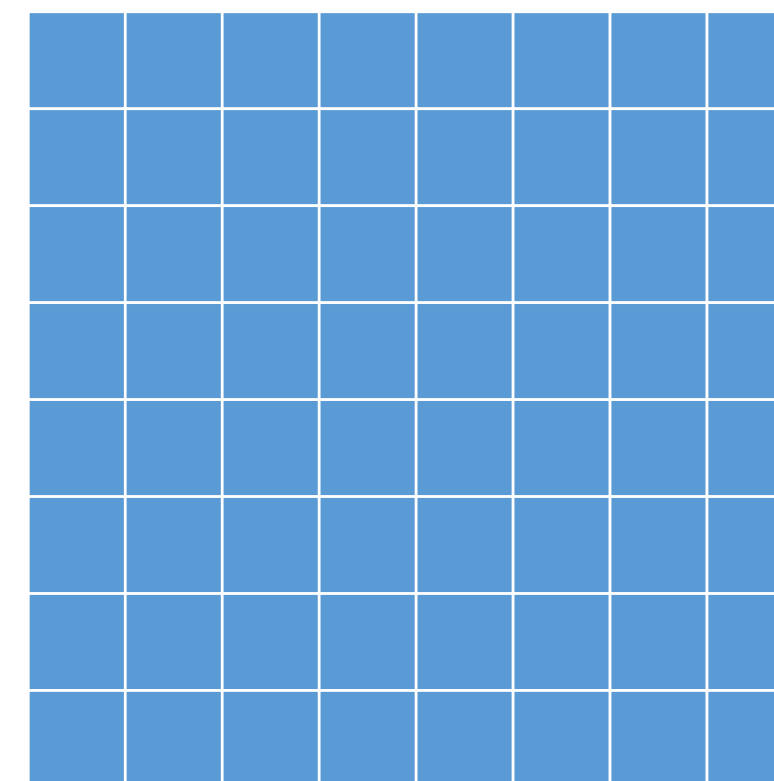
Revisit: GPU Memory Hierarchy



FlashAttention

Key idea: compute attention by blocks to reduce global memory access

$$A = \text{softmax}(QK^T)$$

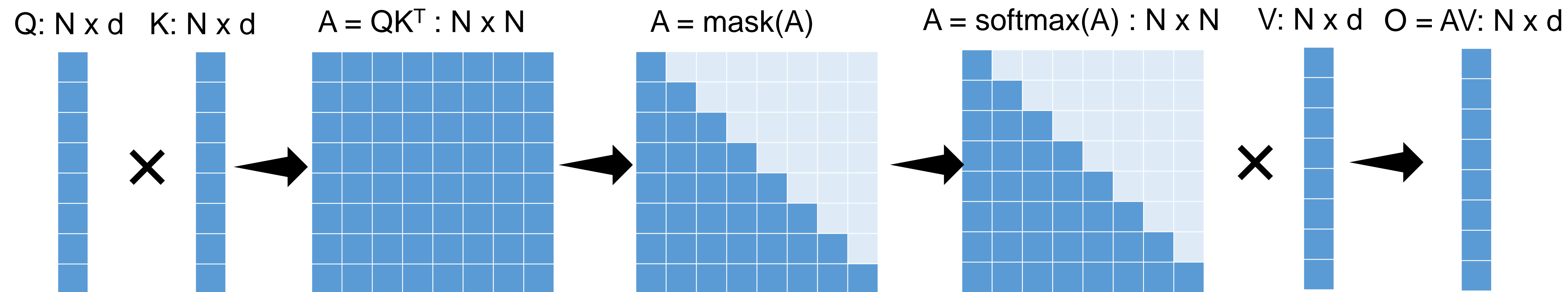


Two main Techniques:

1. Tiling: restructure algorithm to load query/key/value block by block from global to shared memory

2. Recomputation: don't store attention matrix from forward, recompute it in backward

Problem: How to tile softmax?



Challenges

- We must avoid materializing $N \times N$ while still get the precise softmax results
 - Compute softmax reduction w/o access to $N \times N$ at forward
- Backward without the $N \times N$ softmax forward activations

How to Implement Softmax

Algorithm 1 Naive softmax

```
1:  $d_0 \leftarrow 0$ 
2: for  $j \leftarrow 1, V$  do
3:    $d_j \leftarrow d_{j-1} + e^{x_j}$ 
4: end for
5: for  $i \leftarrow 1, V$  do
6:    $y_i \leftarrow \frac{e^{x_i}}{d_V}$ 
7: end for
```

Problem

- Can easily go overflow because of sum (e^x)

Safe Softmax

$$y_i = \frac{e^{x_i - \max_{k=1}^V x_k}}{\sum_{j=1}^V e^{x_j - \max_{k=1}^V x_k}}$$

Algorithm 2 Safe softmax

```
1:  $m_0 \leftarrow -\infty$ 
2: for  $k \leftarrow 1, V$  do
3:    $m_k \leftarrow \max(m_{k-1}, x_k)$ 
4: end for
5:  $d_0 \leftarrow 0$ 
6: for  $j \leftarrow 1, V$  do
7:    $d_j \leftarrow d_{j-1} + e^{x_j - m_V}$ 
8: end for
9: for  $i \leftarrow 1, V$  do
10:   $y_i \leftarrow \frac{e^{x_i - m_V}}{d_V}$ 
11: end for
```

Can we fuse?

Create alternative
sequence

$$d'_i := \sum_{j=1}^i e^{x_j - m_i}$$

With:
 $d'_V = d_V$

Algorithm 2 Safe softmax

```
1:  $m_0 \leftarrow -\infty$ 
2: for  $k \leftarrow 1, V$  do
3:    $m_k \leftarrow \max(m_{k-1}, x_k)$ 
4: end for
5:  $d_0 \leftarrow 0$ 
6: for  $j \leftarrow 1, V$  do
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8: end for
9: for  $i \leftarrow 1, V$  do
10:   $y_i \leftarrow \frac{e^{x_i - m_V}}{d_V}$ 
11: end for
```

But:

Create alternative
sequence

$$d'_i := \sum_{j=1}^i e^{x_j - m_i}$$

With:
 $d'_V = d_V$

$$\begin{aligned} d'_i &= \sum_{j=1}^i e^{x_j - m_i} \\ &= \left(\sum_{j=1}^{i-1} e^{x_j - m_i} \right) + e^{x_i - m_i} \\ &= \left(\sum_{j=1}^{i-1} e^{x_j - m_{i-1}} \right) e^{m_{i-1} - m_i} + e^{x_i - m_i} \\ &= d'_{i-1} e^{m_{i-1} - m_i} + e^{x_i - m_i} \end{aligned}$$

d_V does not
depend on m_V

Online, Safe Softmax

Algorithm 3 Safe softmax with online normalizer calculation

```
1:  $m_0 \leftarrow -\infty$ 
2:  $d_0 \leftarrow 0$ 
3: for  $j \leftarrow 1, V$  do
4:    $m_j \leftarrow \max(m_{j-1}, x_j)$ 
5:    $d_j \leftarrow d_{j-1} \times e^{m_{j-1} - m_j} + e^{x_j - m_j}$ 
6: end for
7: for  $i \leftarrow 1, V$  do
8:    $y_i \leftarrow \frac{e^{x_i - m_V}}{d_V}$ 
9: end for
```

Self attention

NOTATIONS

$Q[k,:]$: the k -th row vector of Q matrix.

$K^T[:,i]$: the i -th column vector of K^T matrix.

$O[k,:]$: the k -th row of output O matrix.

$V[i,:]$: the i -th row of V matrix.

$\{\mathbf{o}_i\}$: $\sum_{j=1}^i a_j V[j,:]$, a row vector storing partial aggregation result $A[k,:i] \times V[:i,:]$

BODY

for $i \leftarrow 1, N$ **do**

$$x_i \leftarrow Q[k,:] K^T[:,i]$$

$$m_i \leftarrow \max(m_{i-1}, x_i)$$

$$d'_i \leftarrow d'_{i-1} e^{m_{i-1}-m_i} + e^{x_i-m_i}$$

end

for $i \leftarrow 1, N$ **do**

$$a_i \leftarrow \frac{e^{x_i-m_N}}{d'_N}$$

$$\mathbf{o}_i \leftarrow \mathbf{o}_{i-1} + a_i V[i,:]$$

end

$$O[k,:] \leftarrow \mathbf{o}_N$$

Self attention

NOTATIONS

$Q[k,:]$: the k -th row vector of Q matrix.

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BODY

for $i \leftarrow 1, N$ **do**

$$\begin{aligned}x_i &\leftarrow Q[k,:] K^T[:,i] \\m_i &\leftarrow \max(m_{i-1}, x_i) \\d'_i &\leftarrow d'_{i-1} e^{m_{i-1}-m_i} + e^{x_i-m_i}\end{aligned}$$

end

for $i \leftarrow 1, N$ **do**

$$\begin{aligned}a_i &\leftarrow \frac{e^{x_i-m_N}}{d'_N} \\ \mathbf{o}_i &\leftarrow \mathbf{o}_{i-1} + a_i V[i,:]\end{aligned}$$

end

$$O[k,:] \leftarrow \mathbf{o}_N$$

$$\mathbf{o}_i := \sum_{j=1}^i \left(\frac{e^{x_j-m_N}}{d'_N} V[j,:] \right)$$

Create alternative sequence with $O_N = \mathbf{o}'_N$

$$\mathbf{o}'_i := \left(\sum_{j=1}^i \frac{e^{x_j-m_i}}{d'_i} V[j,:] \right)$$

But

$$\begin{aligned}
 \mathbf{o}'_i &= \sum_{j=1}^i \frac{e^{x_j - m_i}}{d'_i} V[j, :] \\
 &= \left(\sum_{j=1}^{i-1} \frac{e^{x_j - m_i}}{d'_i} V[j, :] \right) + \frac{e^{x_i - m_i}}{d'_i} V[i, :] \\
 &= \left(\sum_{j=1}^{i-1} \frac{e^{x_j - m_{i-1}}}{d'_{i-1}} \frac{e^{x_j - m_i}}{e^{x_j - m_{i-1}}} \frac{d'_{i-1}}{d'_i} V[j, :] \right) + \frac{e^{x_i - m_i}}{d'_i} V[i, :] \\
 &= \left(\sum_{j=1}^{i-1} \frac{e^{x_j - m_{i-1}}}{d'_{i-1}} V[j, :] \right) \frac{d'_{i-1}}{d'_i} e^{m_{i-1} - m_i} + \frac{e^{x_i - m_i}}{d'_i} V[i, :] \\
 &= \mathbf{o}'_{i-1} \frac{d'_{i-1} e^{m_{i-1} - m_i}}{d'_i} + \frac{e^{x_i - m_i}}{d'_i} V[i, :]
 \end{aligned}$$

for $i \leftarrow 1, N$ do

$$\begin{aligned}
 x_i &\leftarrow Q[k, :] K^T[:, i] \\
 m_i &\leftarrow \max(m_{i-1}, x_i) \\
 d'_i &\leftarrow d'_{i-1} e^{m_{i-1} - m_i} + e^{x_i - m_i} \\
 \mathbf{o}'_i &\leftarrow \mathbf{o}'_{i-1} \frac{d'_{i-1} e^{m_{i-1} - m_i}}{d'_i} + \frac{e^{x_i - m_i}}{d'_i} V[i, :]
 \end{aligned}$$

end

$$O[k, :] \leftarrow \mathbf{o}'_N$$

Flash Attention

for $i \leftarrow 1, N$ **do**

$$x_i \leftarrow Q[k, :] K^T[:, i]$$

$$m_i \leftarrow \max(m_{i-1}, x_i)$$

$$d'_i \leftarrow d'_{i-1} e^{m_{i-1} - m_i} + e^{x_i - m_i}$$

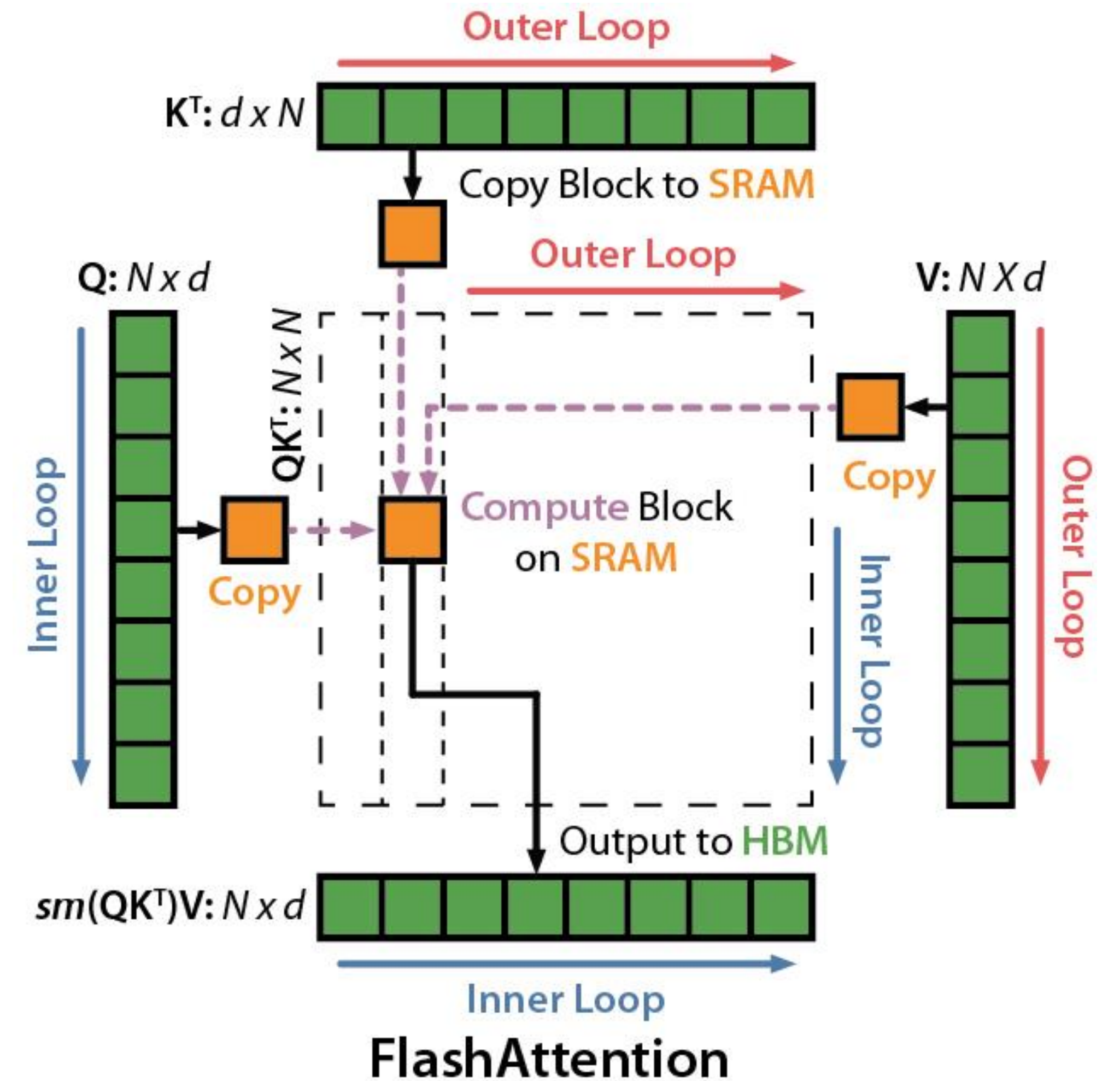
$$\mathbf{o}'_i \leftarrow \mathbf{o}'_{i-1} \frac{d'_{i-1} e^{m_{i-1} - m_i}}{d'_i} + \frac{e^{x_i - m_i}}{d'_i} V[i, :]$$

end

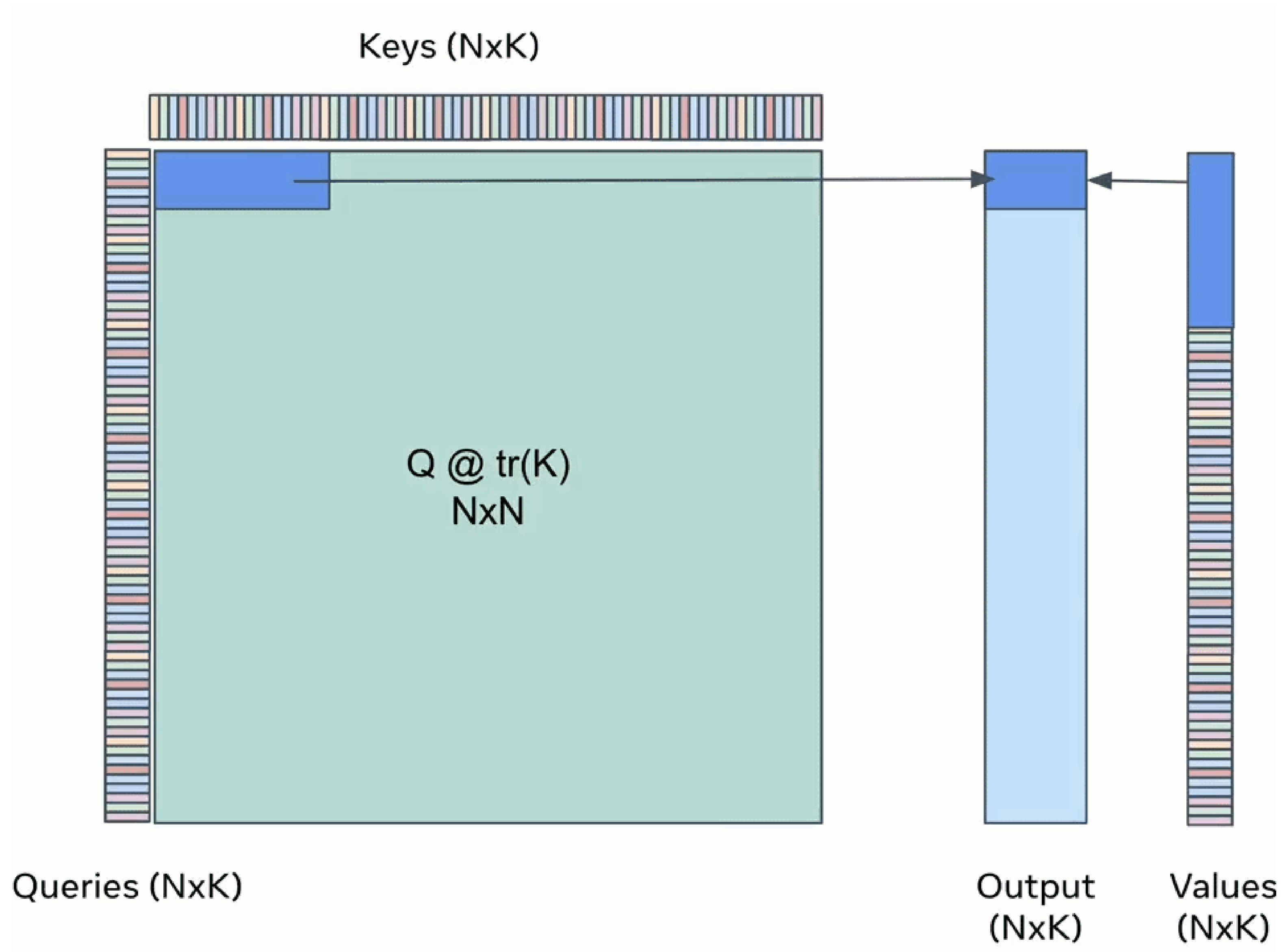
$$O[k, :] \leftarrow \mathbf{o}'_N$$

Tiling: Decompose Large Softmax into smaller ones by Scaling

1. Load inputs by blocks from global to shared memory
2. On chip, compute attention output wrt the block
3. Update output in device memory by scaling



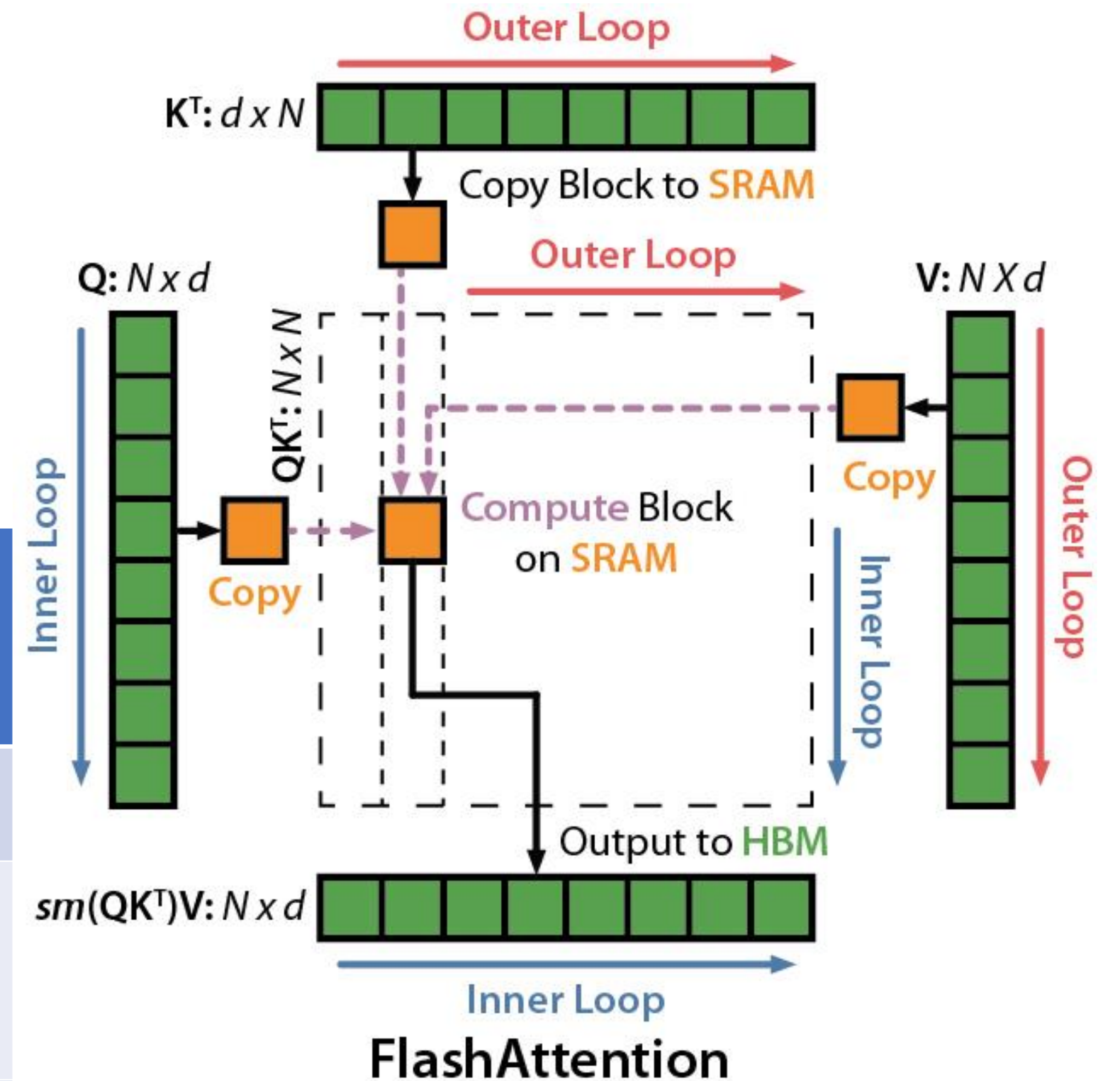
Tiling



Recomputation: Backward Pass

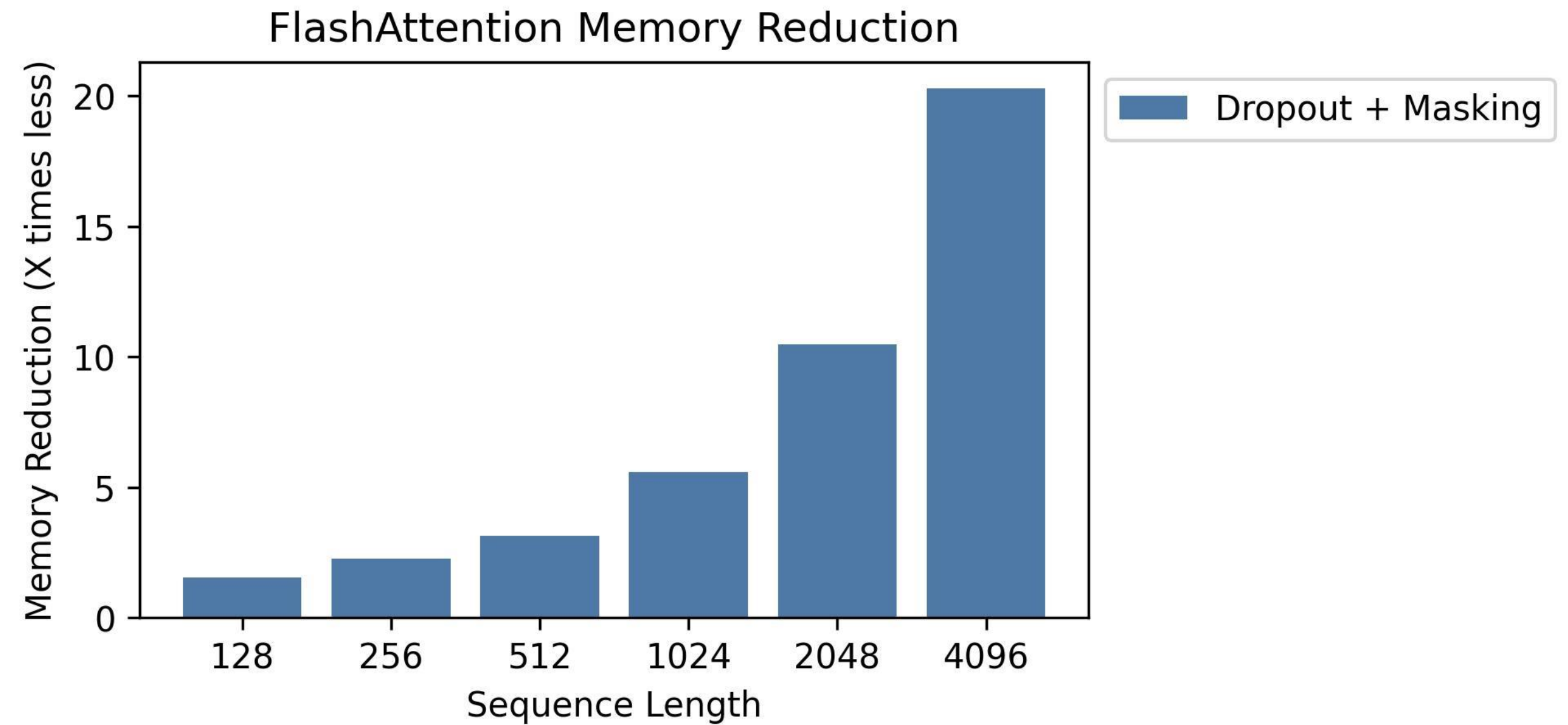
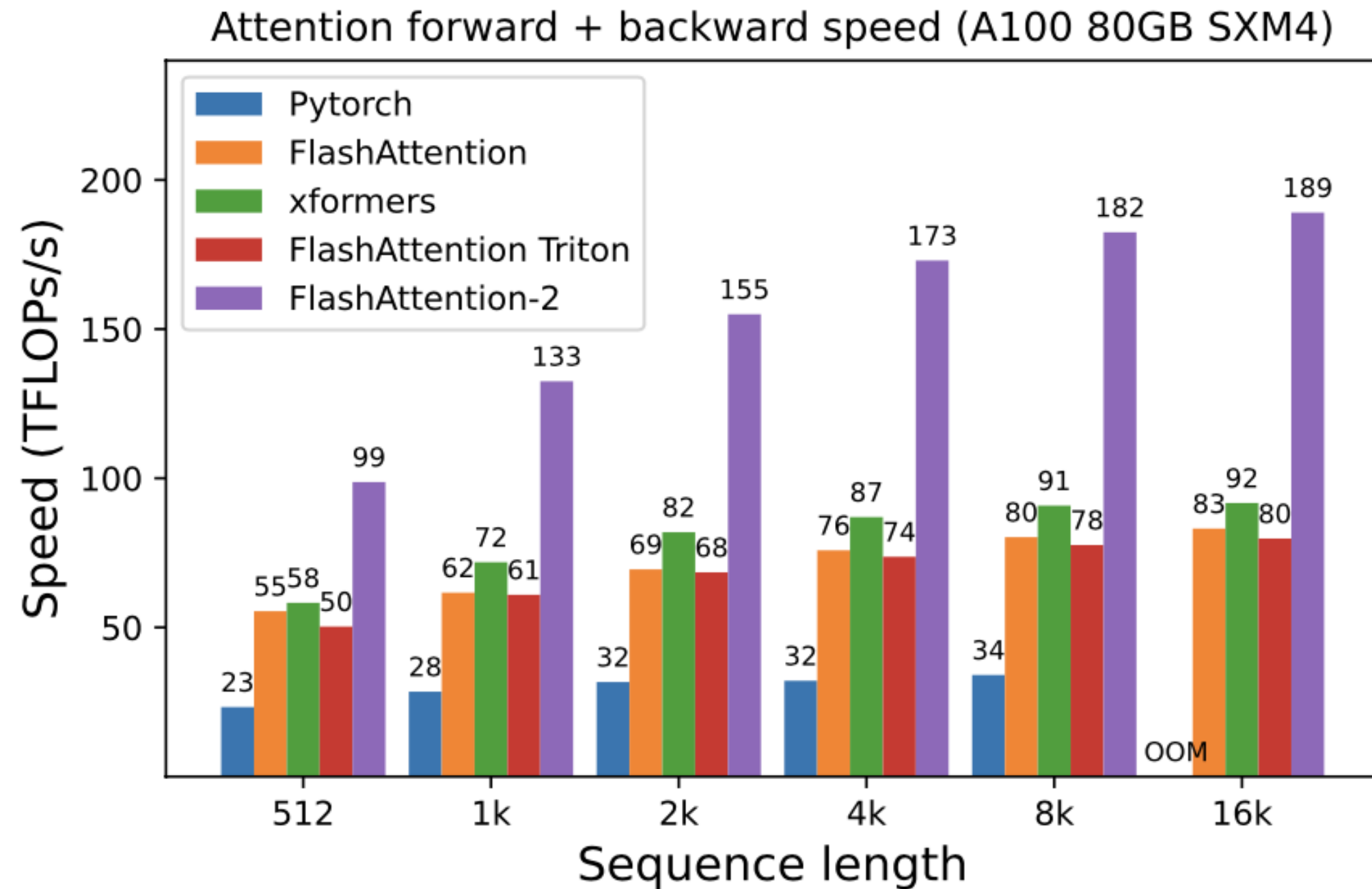
By storing softmax normalization factors from forward (size N), recompute attention in the backward from inputs in shared memory

Attention	Standard	FlashAttention
GFLOPs	66.6	75.2
Global mem access	40.3 GB	4.4 GB
Runtime	41.7 ms	7.3 ms



Speed up backward pass with increased FLOPs

FlashAttention: 2-4x speedup, 10-20x memory reduction

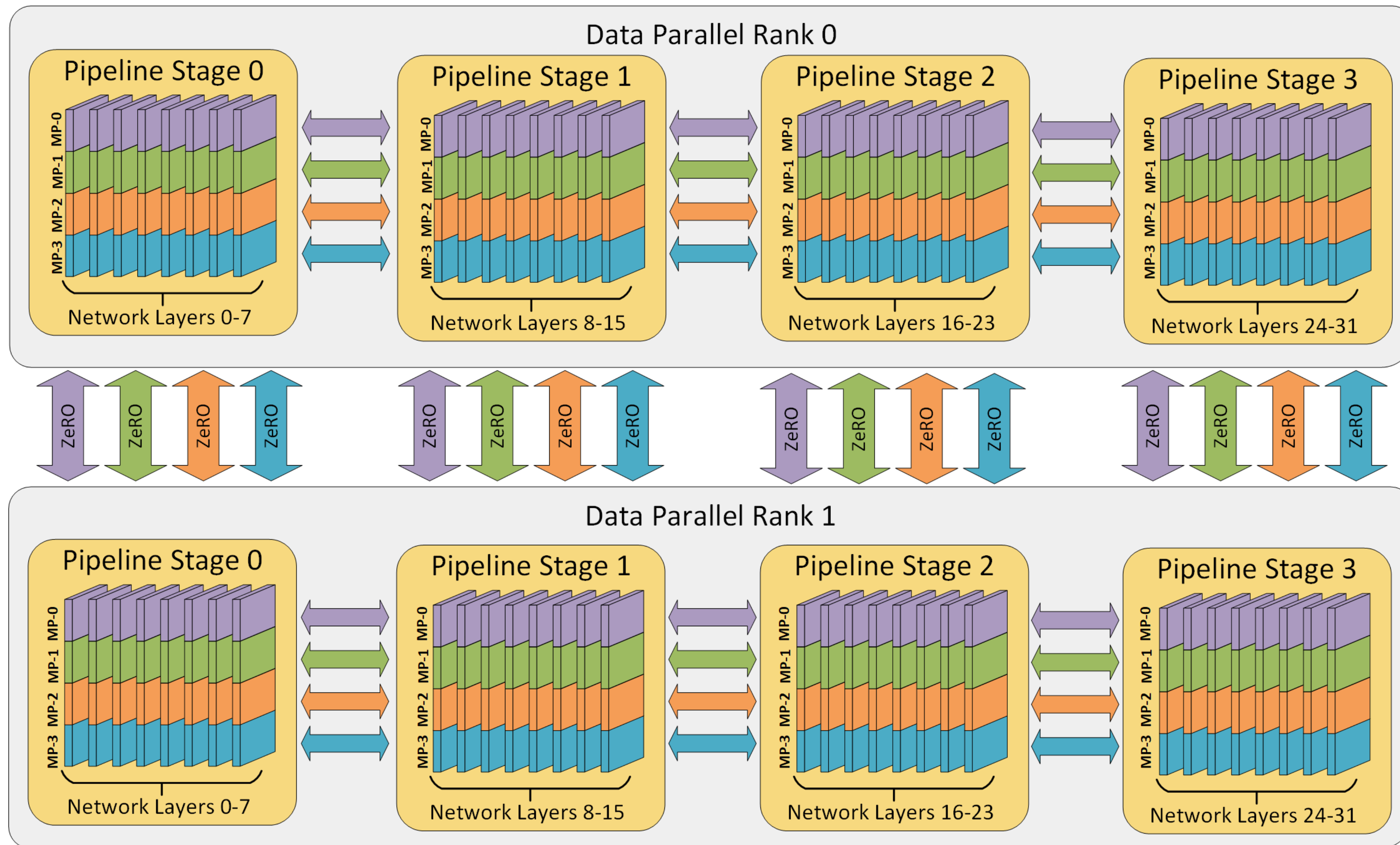


Memory linear in sequence length

Where We Are: LLMs

- Transformers and Attentions
- LLM Training Optimizations
 - Flash attention
 - **3D parallelism**
- LLM Inference and Serving
 - Paged attention
 - Continuous batching
 - Speculative decoding
- Scaling Laws
- Long context

How LLMs are trained today



Summary: How LLMs are trained today

- Outer Loop 1:
 - Inter-op parallelism + 1F1B
- Outer Loop 2: Intra-op parallelism based on model architecture
 - Zero-2 / Zero-3 + data parallelism
 - Megatron-LM tensor parallelism or Expert parallelism
- Outer Loop 3:
 - Gradient checkpointing and recomputation at backward
- Inner Loop 4:
 - Graph fusion
- Inner Loop 5:
 - Operator-level optimization: tiling, flash attention, etc.

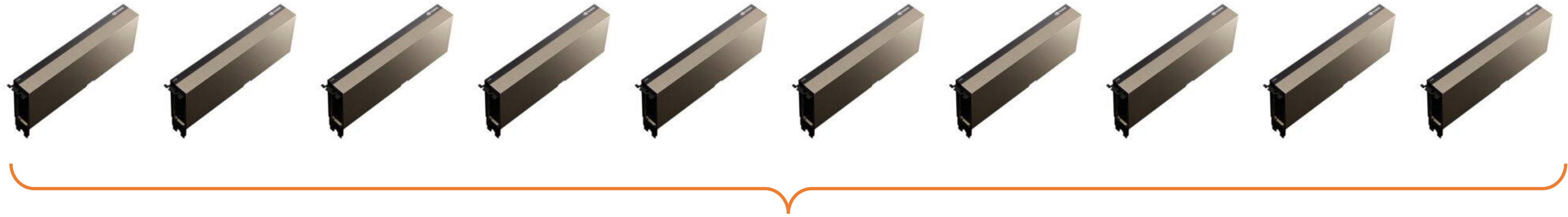
Side effects of Flash Attention

- Because we do not materialize the $N \times N$ intermediate matrix, we decrease peak memory
- Because of decreased peak memory, we can use a larger micro batch size (significantly larger, e.g., 1 \rightarrow 32)
- Because of large per-device batch size, much higher AI

Where We Are: LLMs

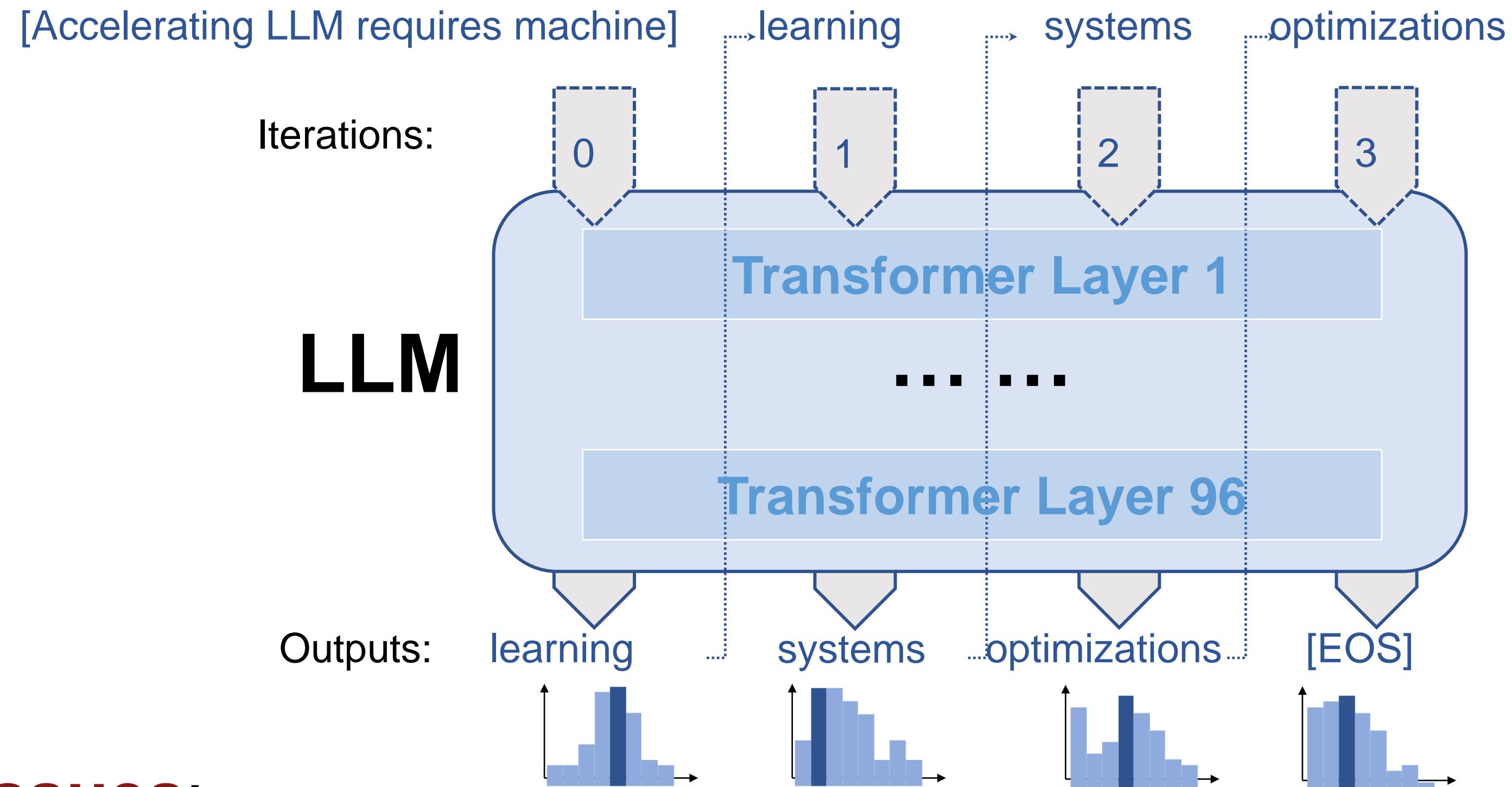
- Transformers and Attentions
- LLM Training Optimizations
 - Flash attention
 - 3D parallelism
- **LLM Inference and Serving**
 - Continuous batching
 - Paged attention
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LLMs are Slow and Expensive to Serve



- **At least ten** A100-40GB GPUs to serve 175B GPT-3 in half precision
- Generating 256 tokens takes **~20 seconds**
- Cannot process many requests in parallel
 - Per-request key/value cache takes **3GB GPU memory**

Recall: Incremental Decoding



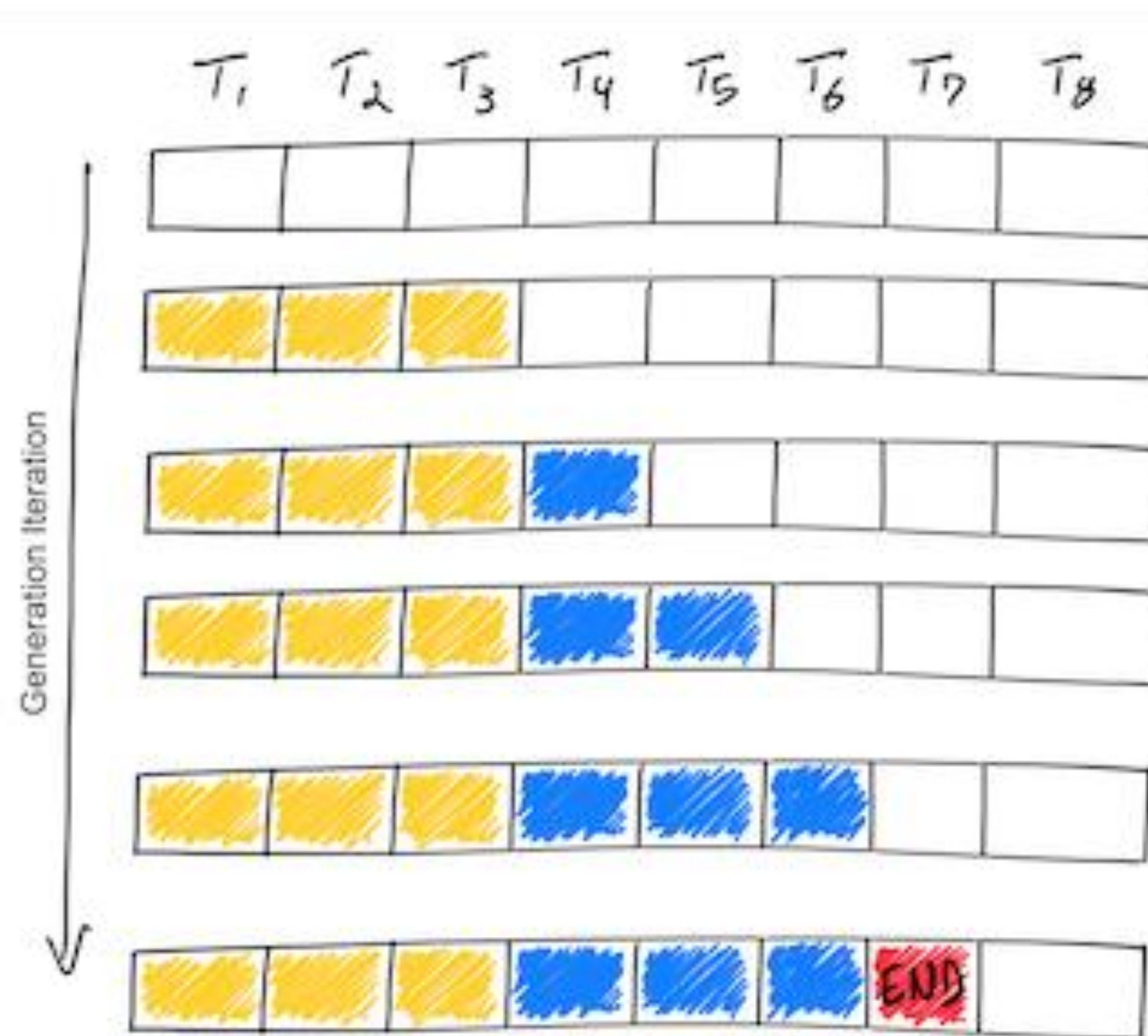
Main issues:

- Limited degree of parallelism → underutilized GPU resources
- Need all parameters to decode a token → bottlenecked by GPU memory access

Outline: LLMs Serving Techniques

- **Continuous Batching**
- Paged Attention
- Speculative Decoding

LLM Decoding Timeline



Batching Requests to Improve GPU Performance

T_1	T_2	T_3	T_4	T_5	T_6	T_7	T_8
S_1	S_1	S_1	S_1				
S_2	S_2	S_2					
S_3	S_3	S_3	S_3				
S_4	S_4	S_4	S_4	S_4			

T_1	T_2	T_3	T_4	T_5	T_6	T_7	T_8
S_1	S_1	S_1	S_1	S_1	END		
S_2	S_2	S_2	S_2	S_2	S_2	S_2	END
S_3	S_3	S_3	S_3	END			
S_4	S_4	S_4	S_4	S_4	S_4	END	

Issues with static batching:

- Requests may complete at different iterations
- Idle GPU cycles
- New requests cannot start immediately

Continuous Batching

T_1	T_2	T_3	T_4	T_5	T_6	T_7	T_8
S_1	S_1	S_1	S_1				
S_2	S_2	S_2					
S_3	S_3	S_3	S_3				
S_4	S_4	S_4	S_4	S_4			

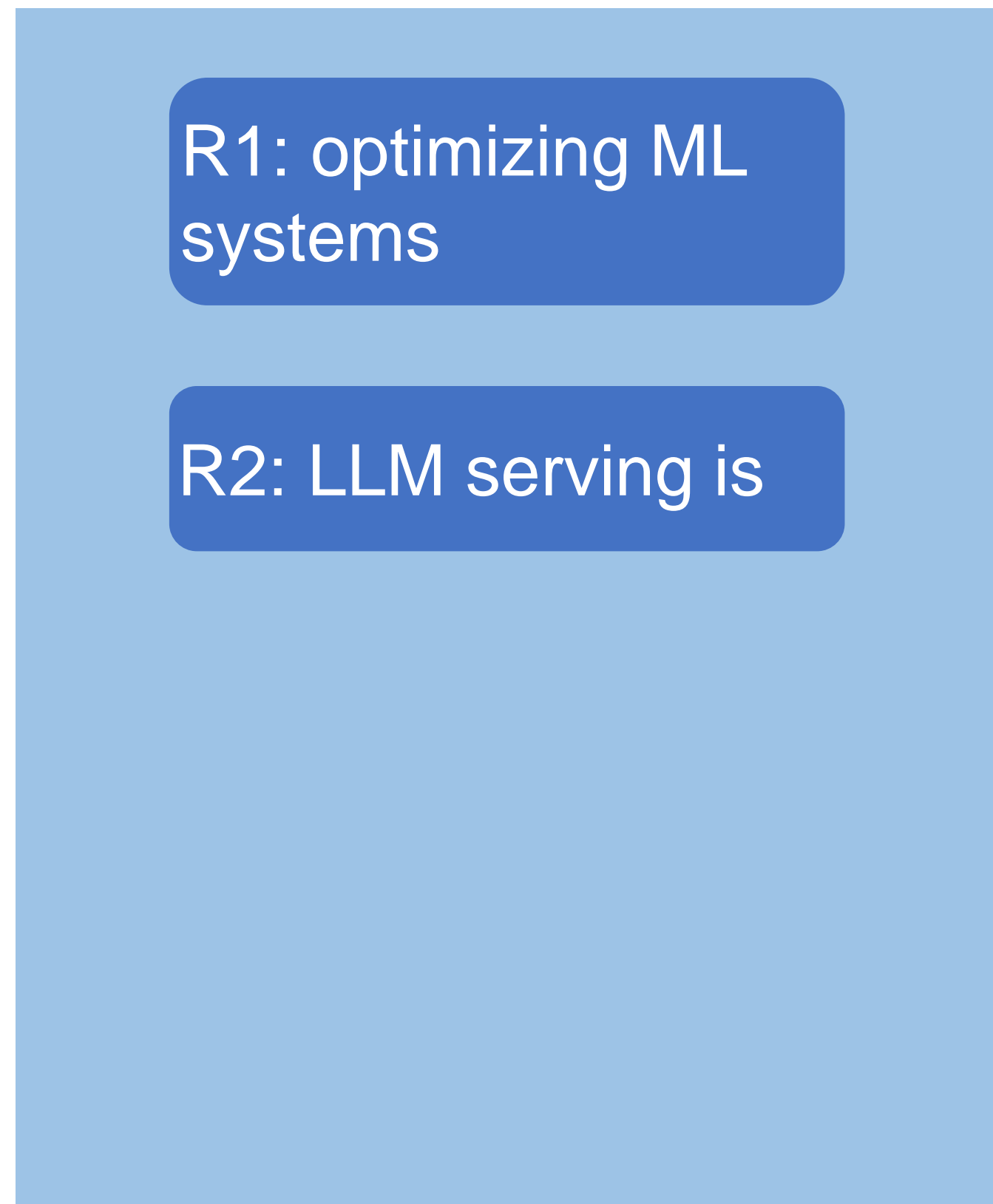
T_1	T_2	T_3	T_4	T_5	T_6	T_7	T_8
S_1	S_1	S_1	S_1	S_1	END	S_6	S_6
S_2	S_2	S_2	S_2	S_2	S_2	S_2	END
S_3	S_3	S_3	S_3	END	S_5	S_5	S_5
S_4	S_4	S_4	S_4	S_4	S_4	END	S_7

Benefits:

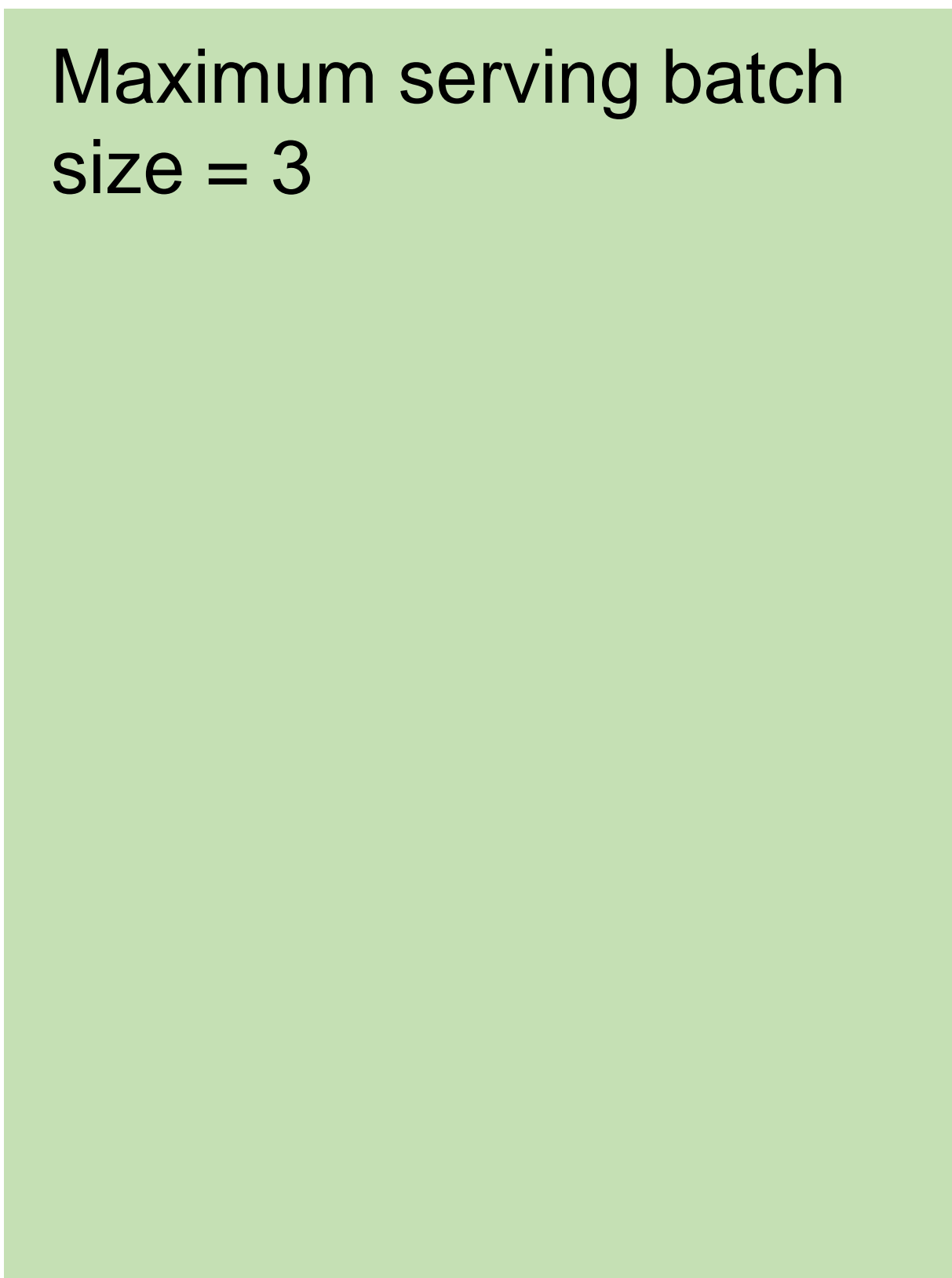
- Higher GPU utilization
- New requests can start immediately

Continuous Batching Step-by-Step

- Receives two new requests R1 and R2



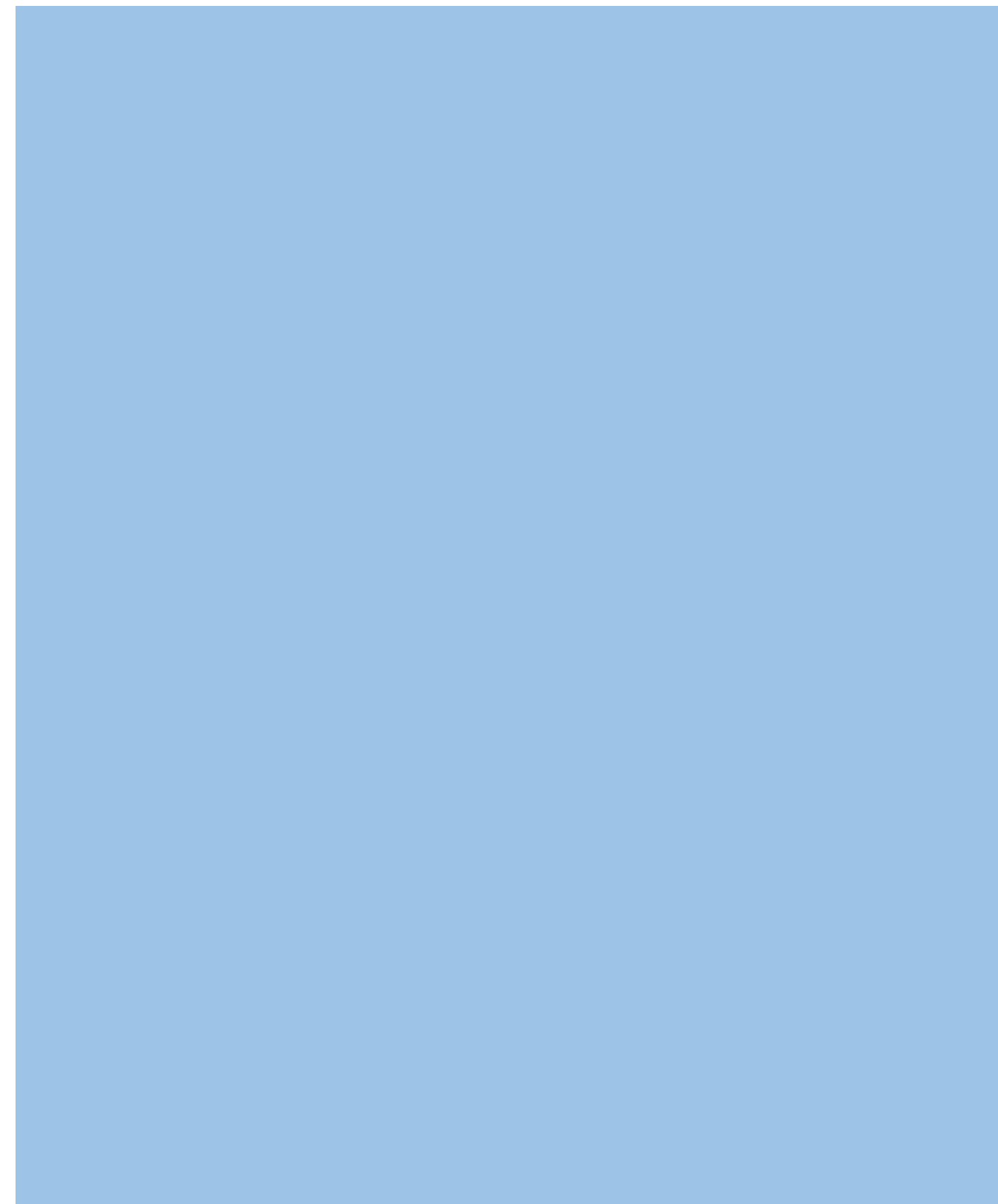
**Request Pool
(CPU)**



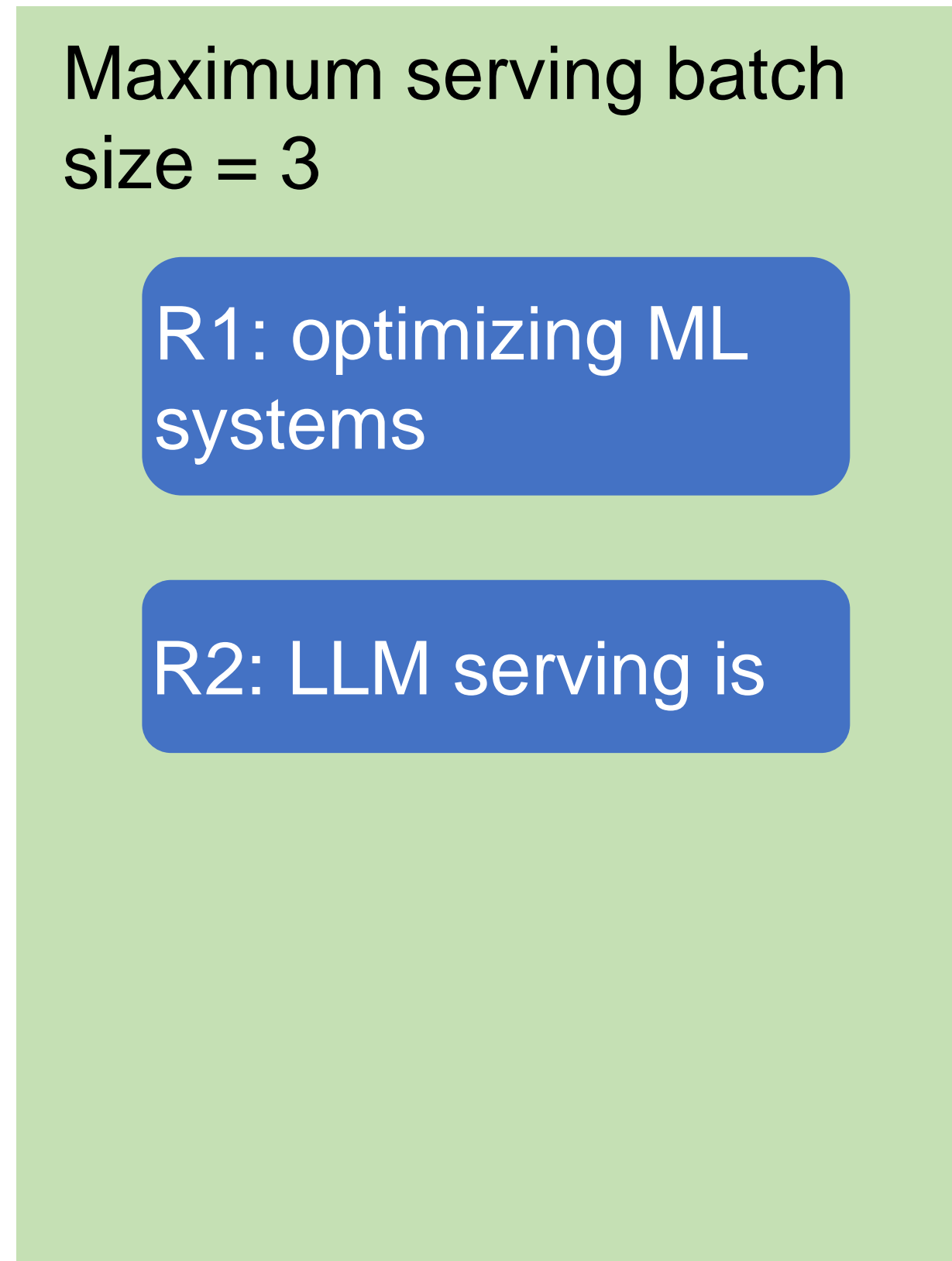
**Execution Engine
(GPU)**

Continuous Batching Step-by-Step

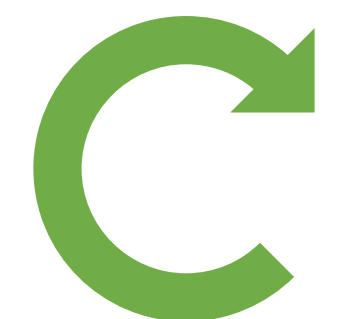
- Iteration 1: decode R1 and R2



**Request Pool
(CPU)**



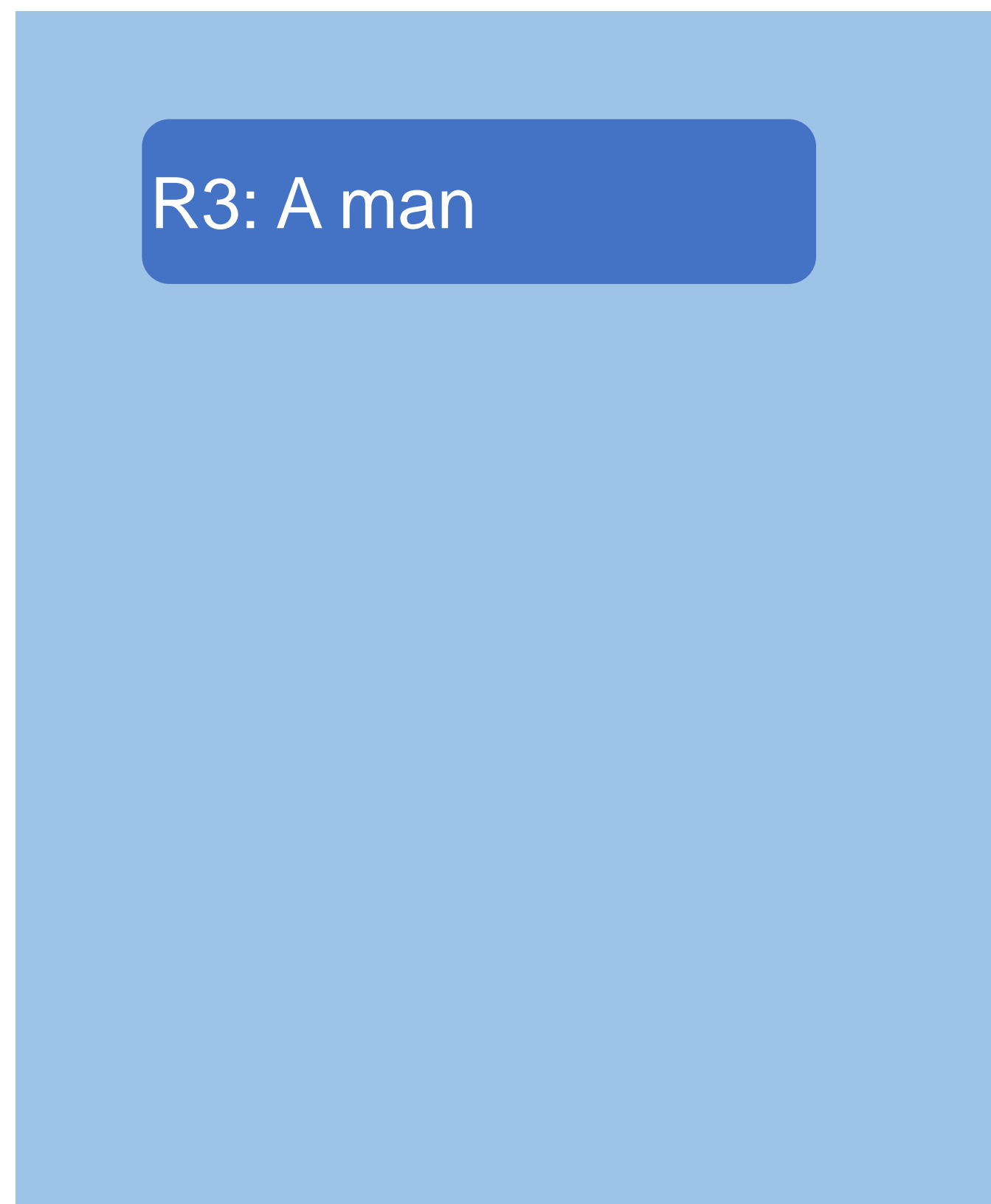
**Execution Engine
(GPU)**



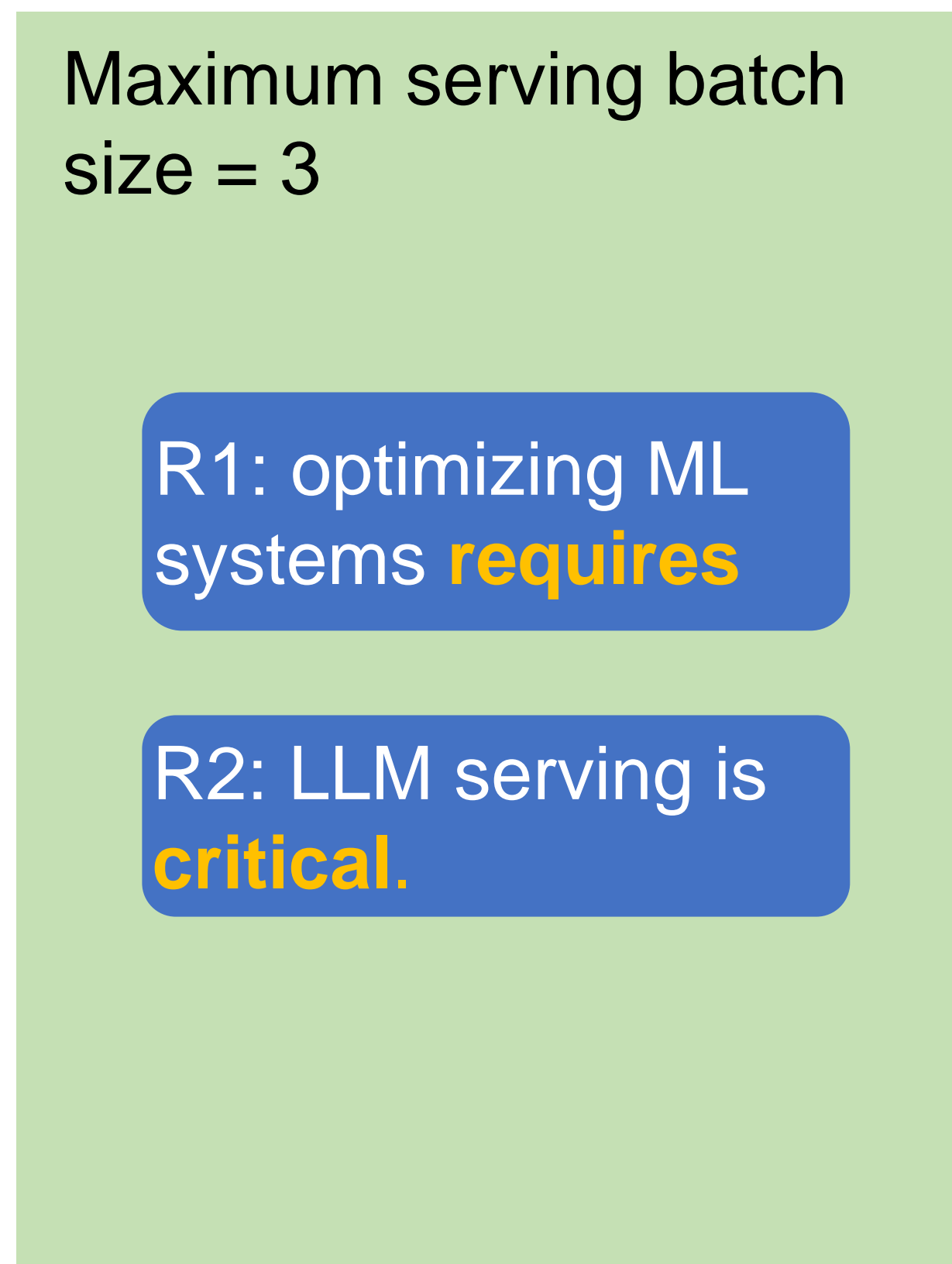
Iteration 1

Continuous Batching Step-by-Step

- Receive a new request R3; finish decoding R1 and R2



Request Pool
(CPU)



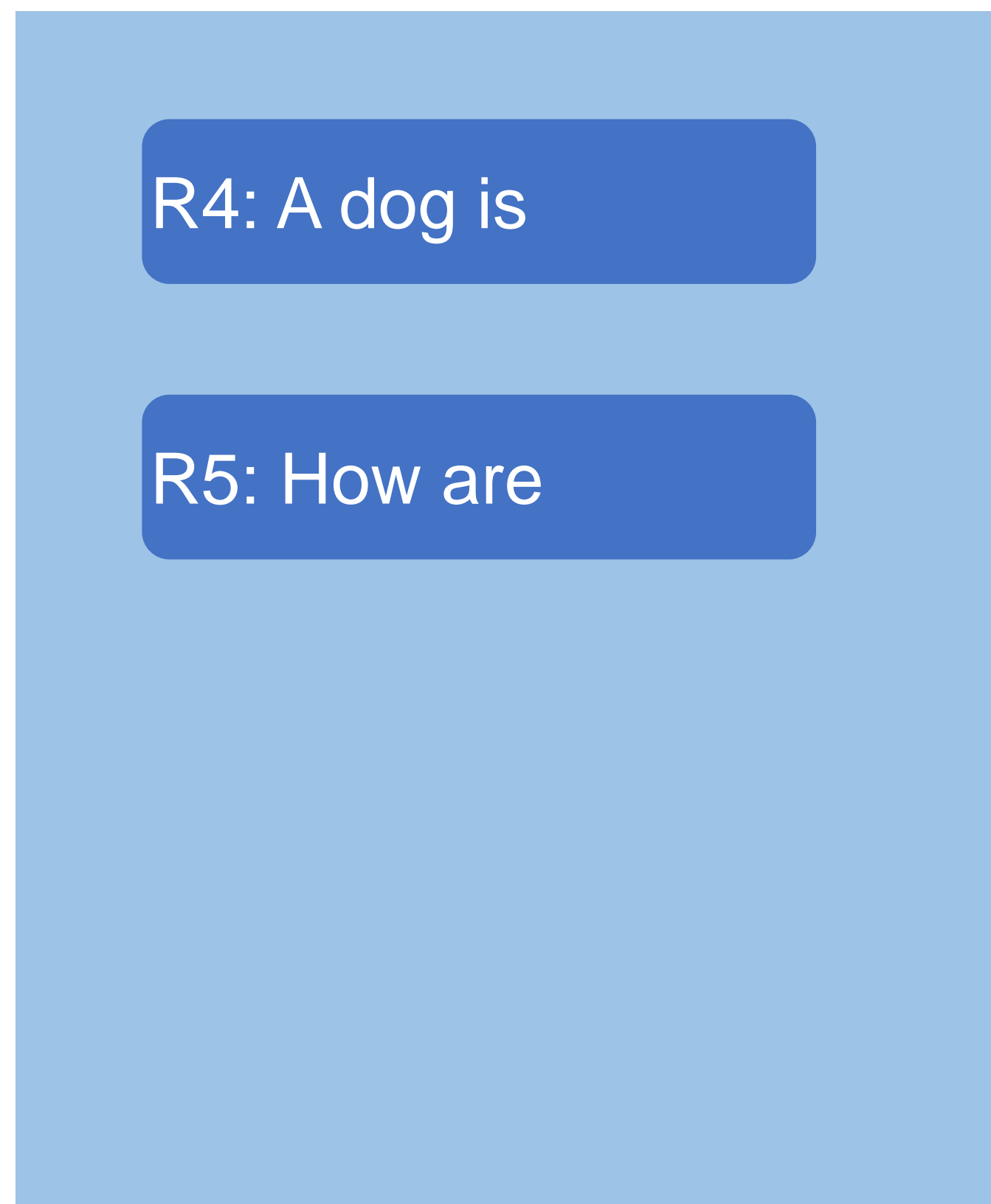
Execution Engine
(GPU)



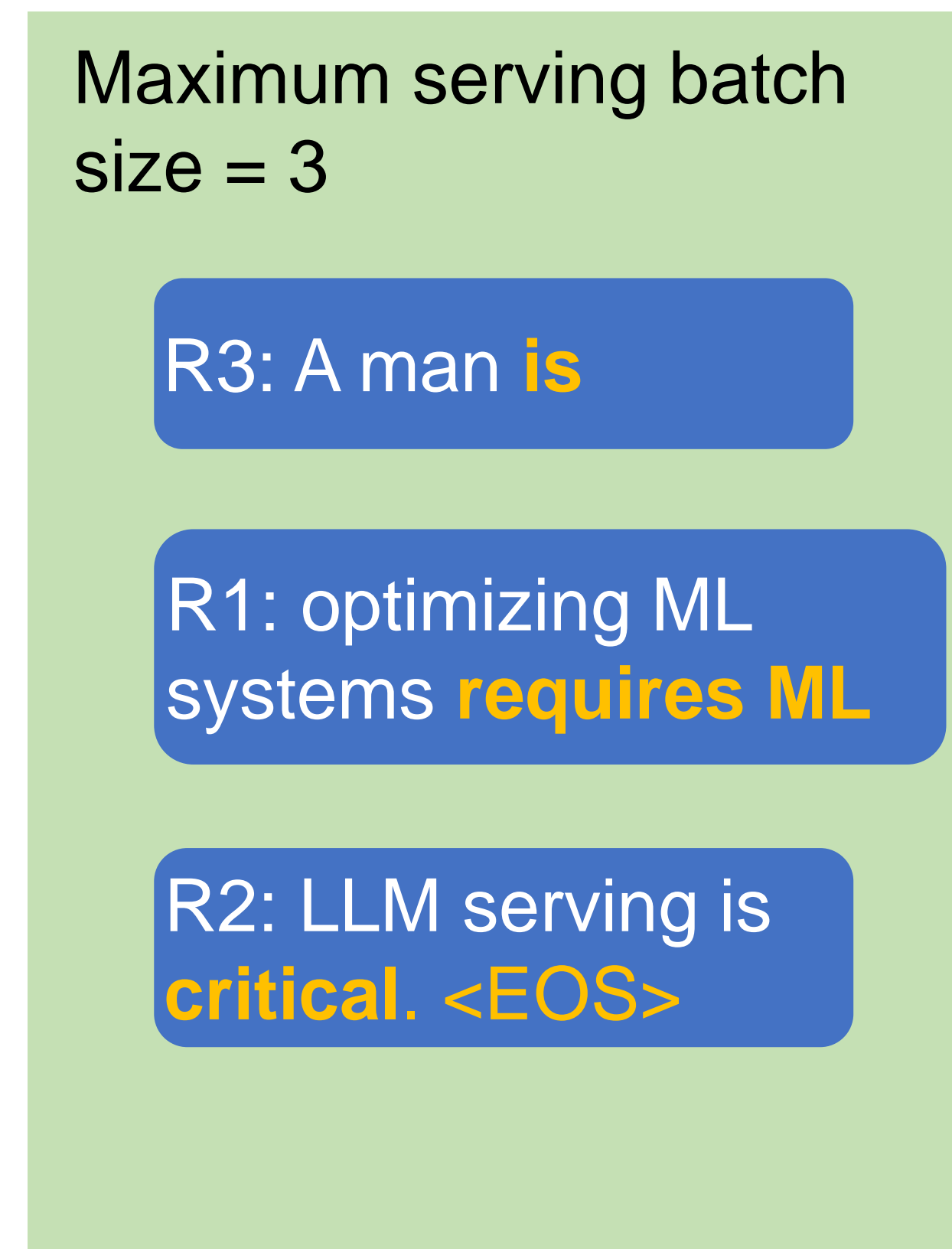
Iteration 1

Continuous Batching Step-by-Step

- Iteration 2: decode R1, R2, R3; receive R4, R5; R2 completes



**Request Pool
(CPU)**

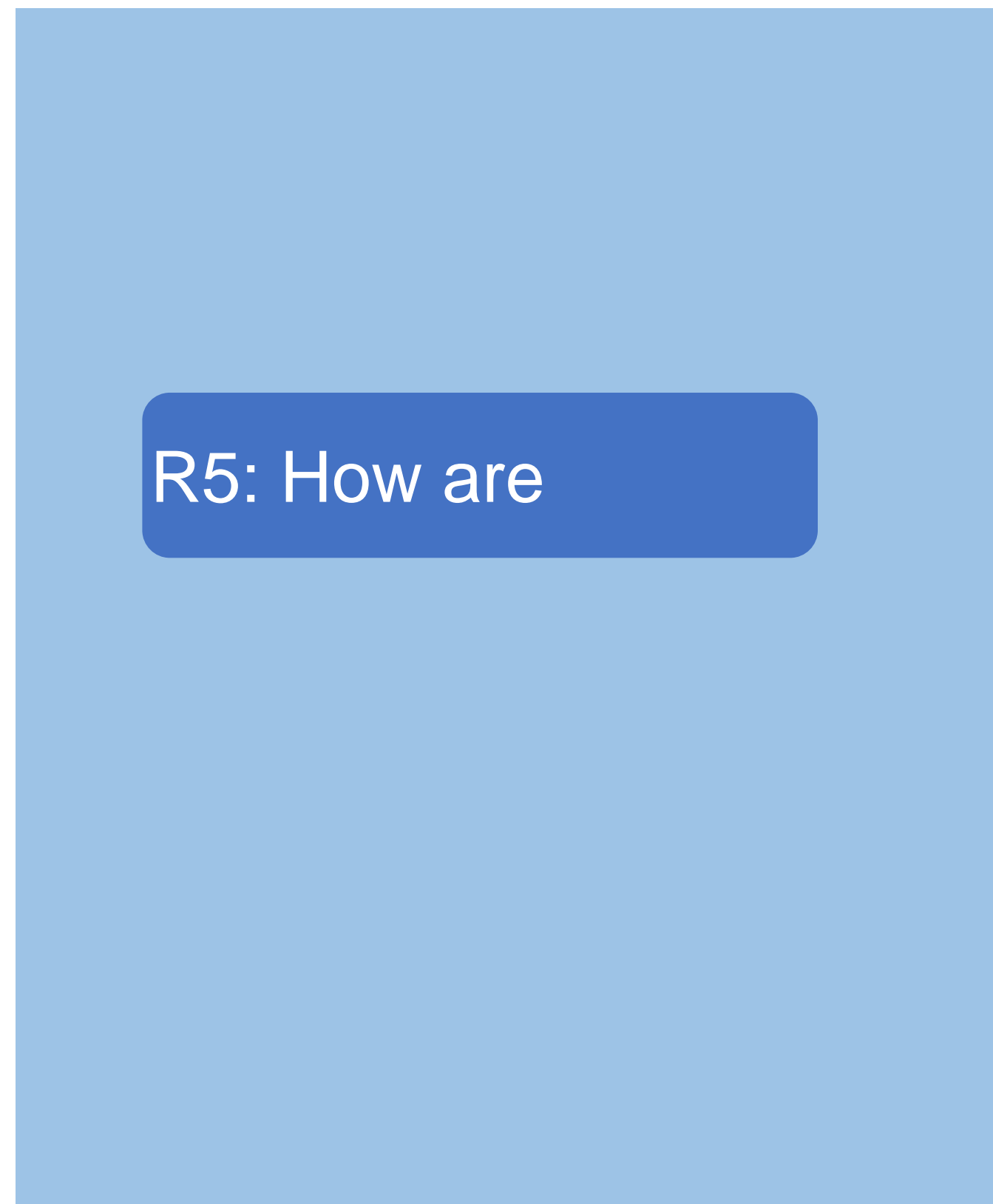


**Execution Engine
(GPU)**

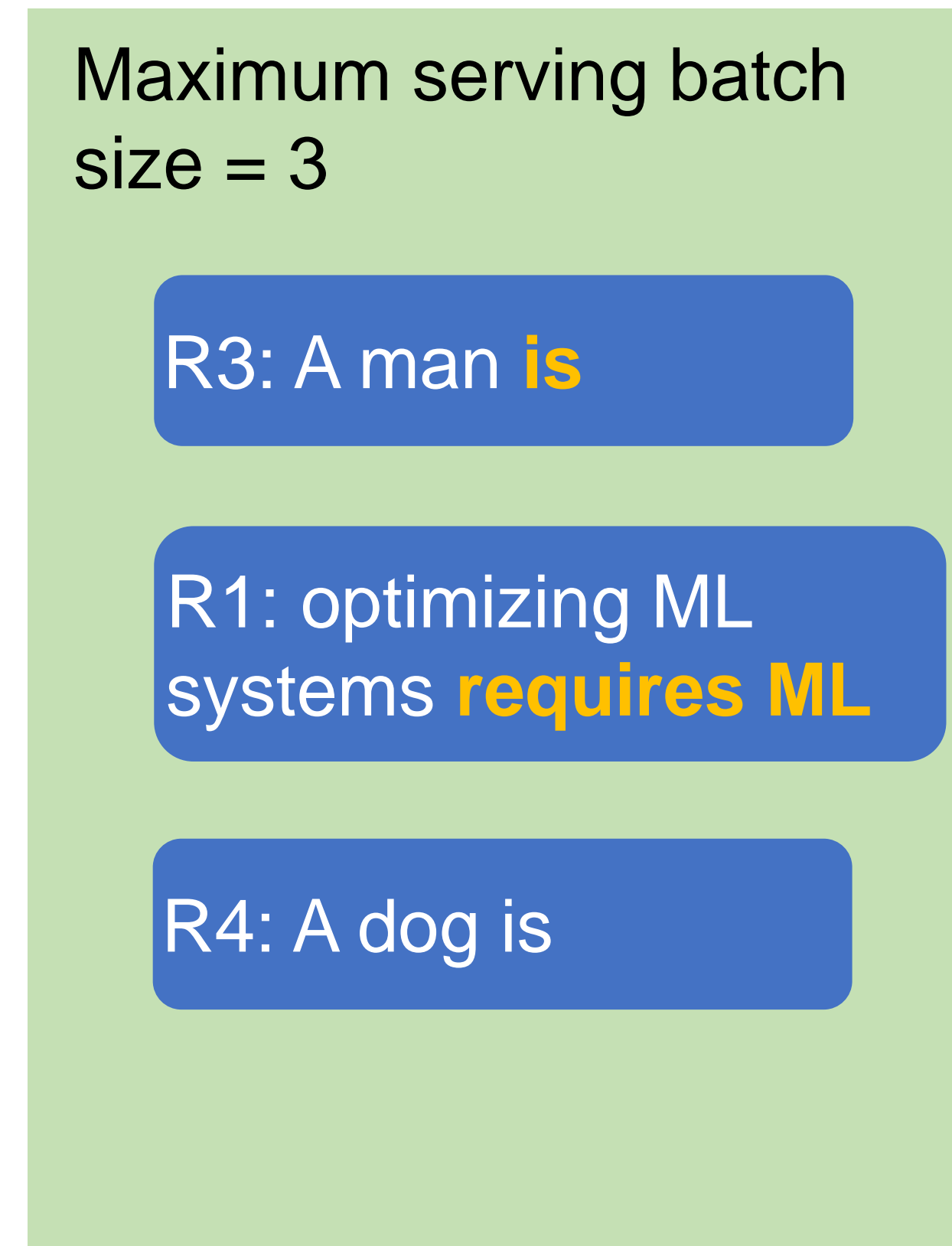


Continuous Batching Step-by-Step

- Iteration 3: decode R1, R3, R4



**Request Pool
(CPU)**



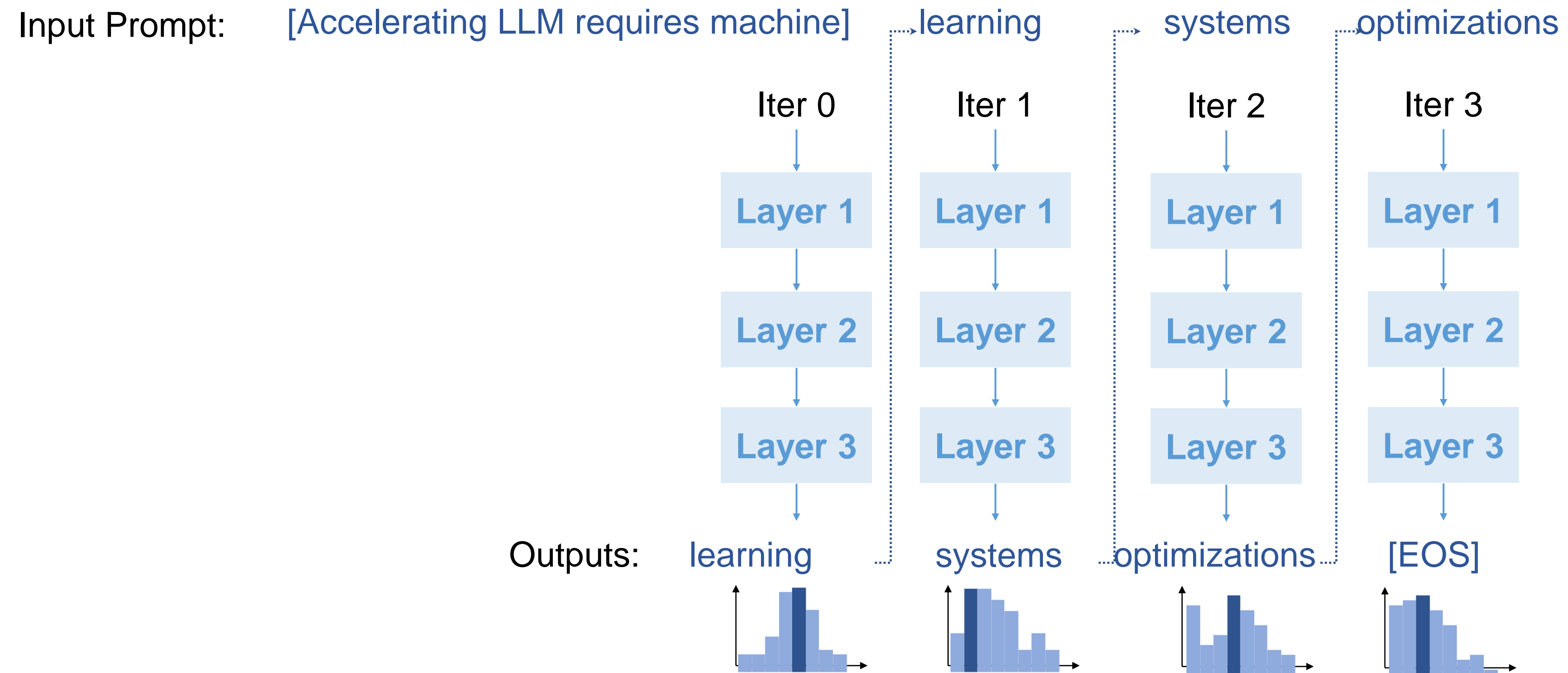
**Execution Engine
(GPU)**



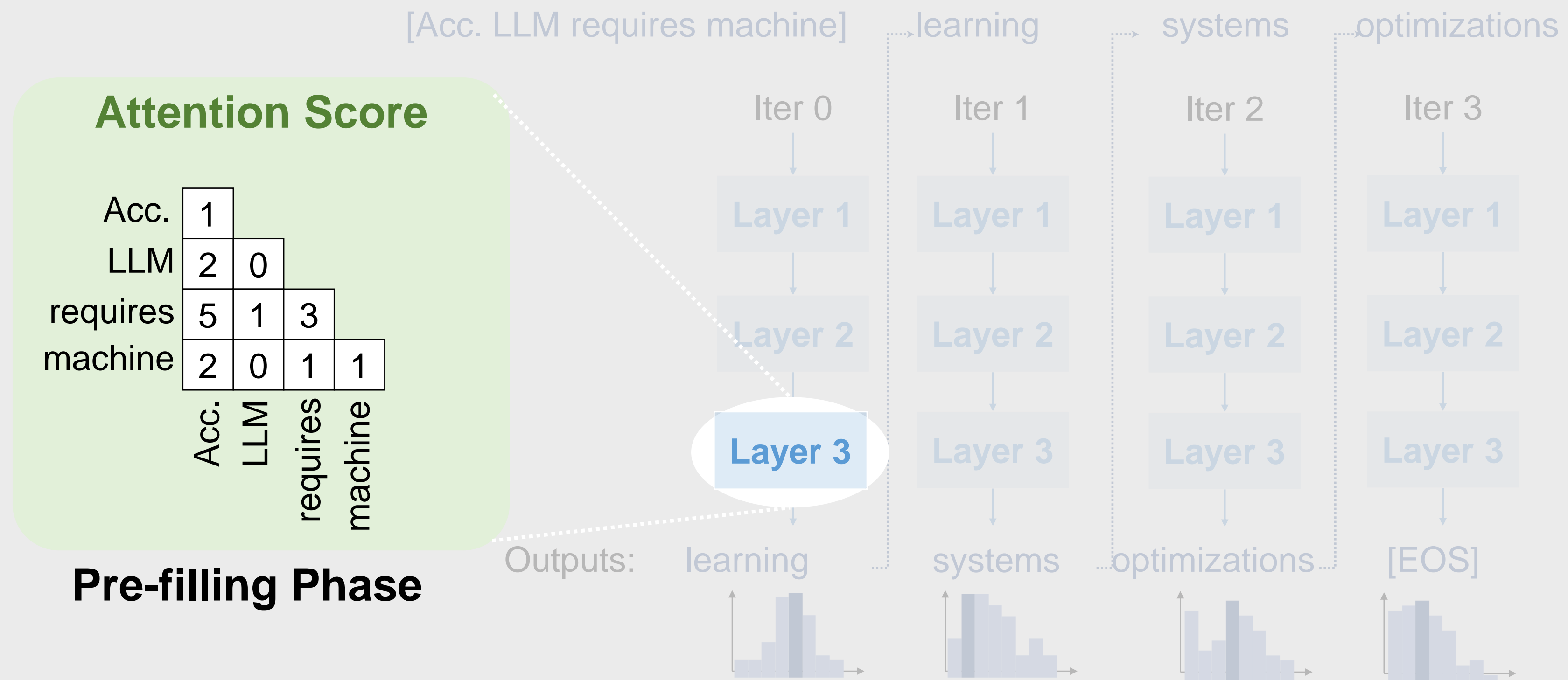
Continuous Batching

- Handle early-finished and late-arrived requests more efficiently
- Higher GPU utilization

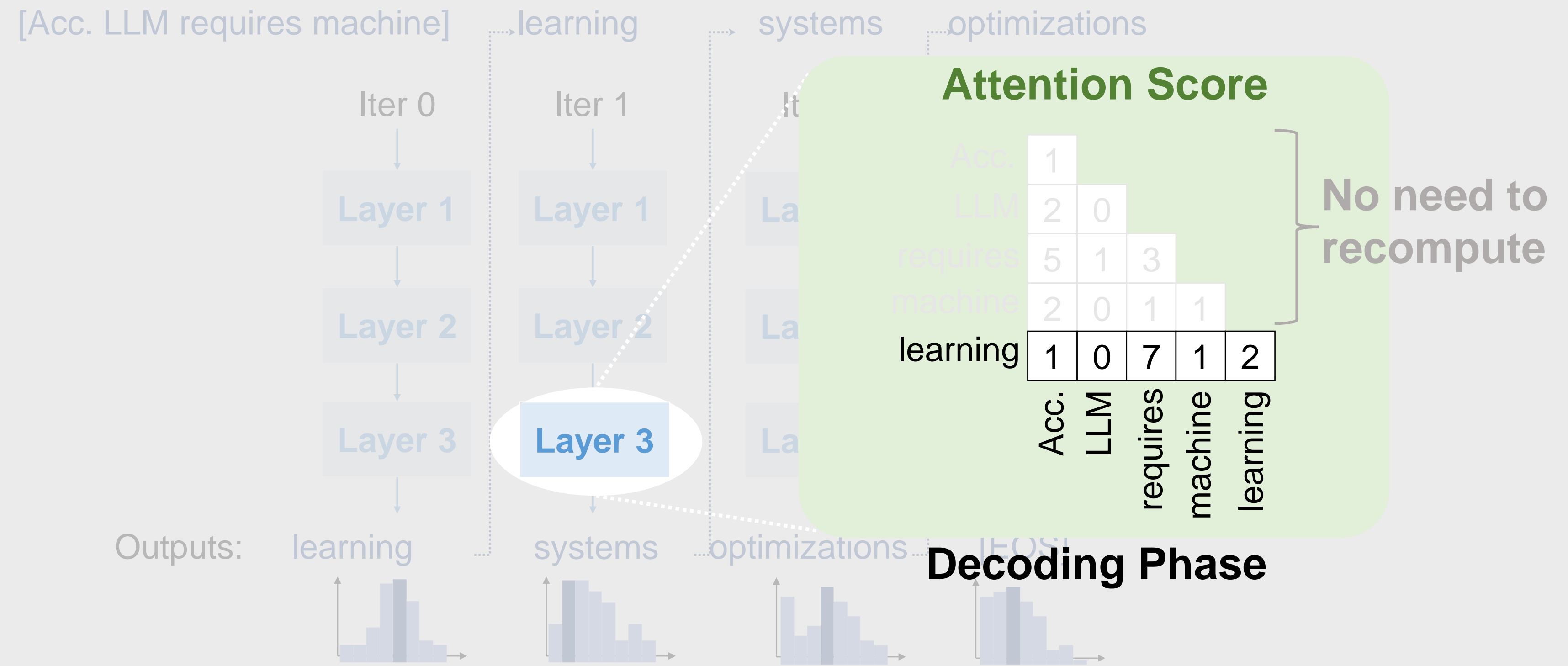
Generative LLM Inference: Autoregressive Decoding



Generative LLM Inference: Autoregressive Decoding



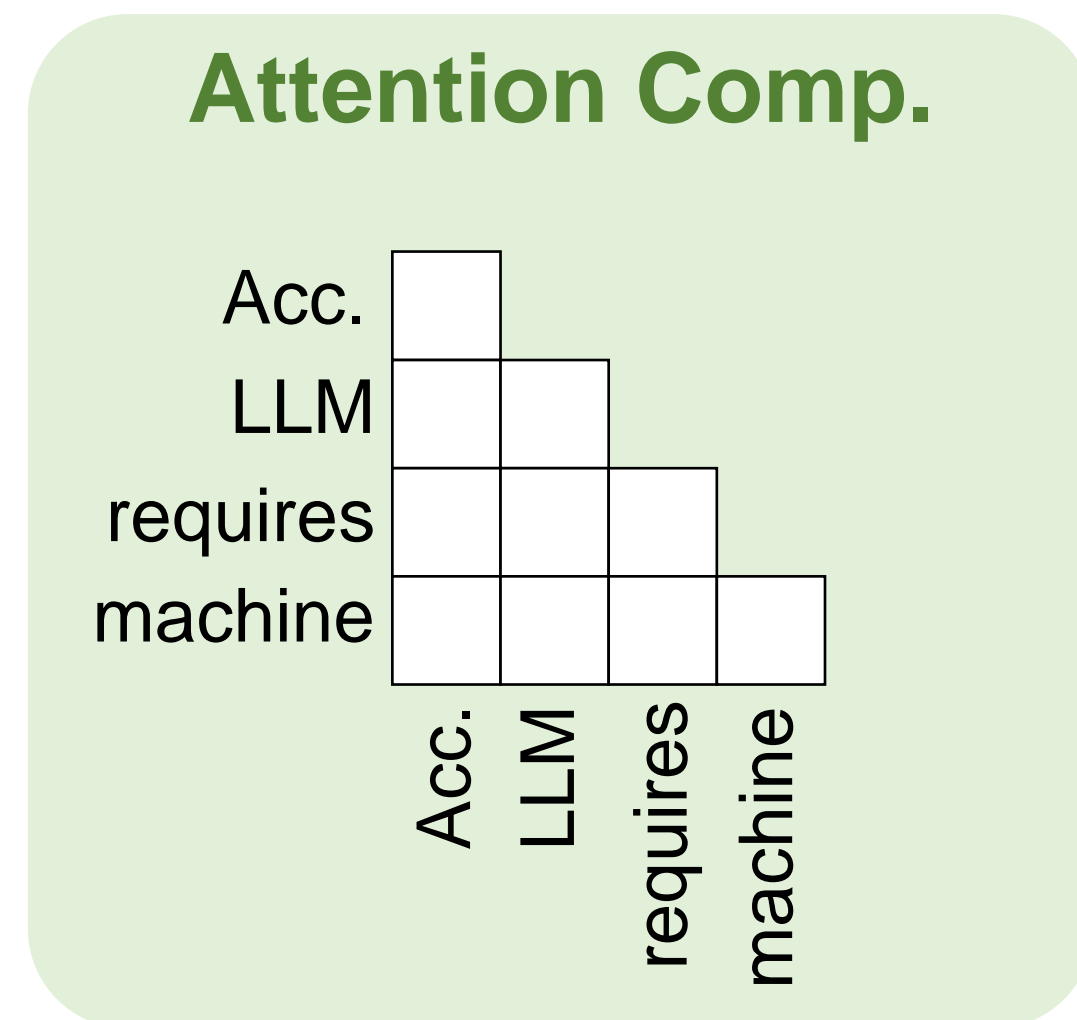
Generative LLM Inference: Autoregressive Decoding



Generative LLM Inference: Autoregressive Decoding

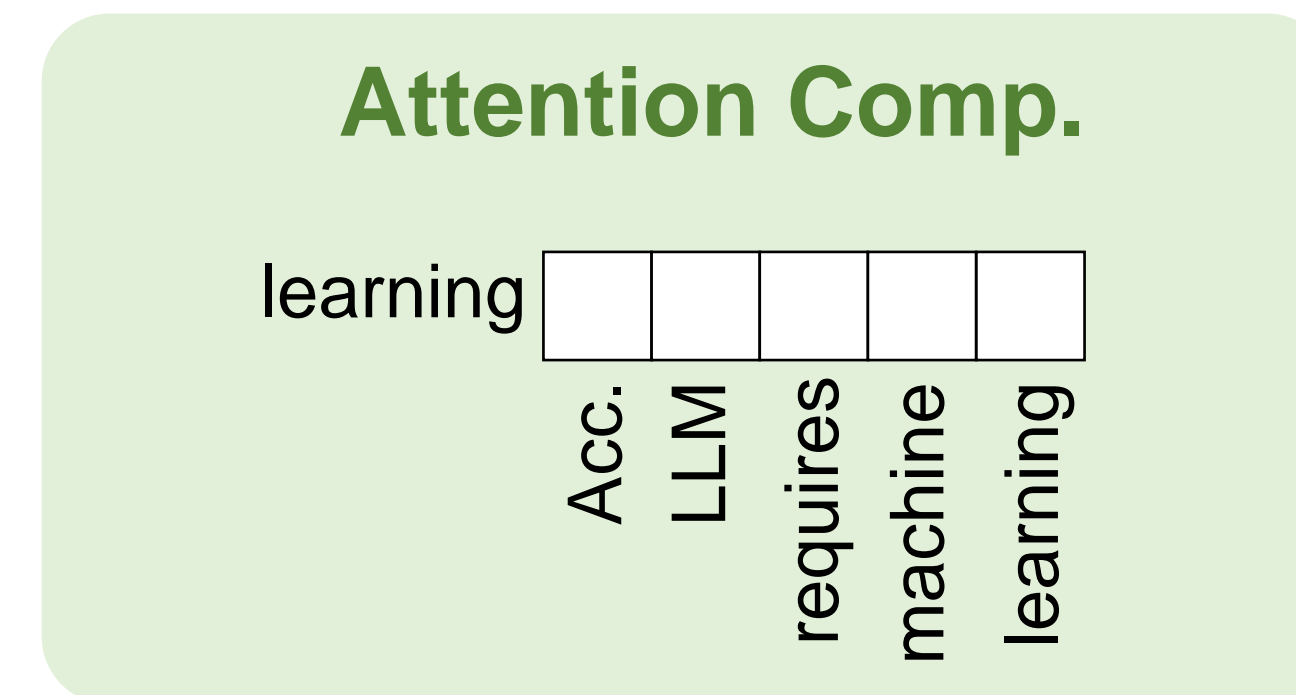
- **Pre-filling phase** (0-th iteration):
 - Process *all* input tokens at once
- **Decoding phase** (all other iterations):
 - Process a *single* token generated from previous iteration
 - Use attention keys & values of all previous tokens
- Key-value cache:
 - Save attention keys and values for the following iterations to avoid recomputation

Can We Apply FlashAttention to LLM Inference?



Pre-filling phase:

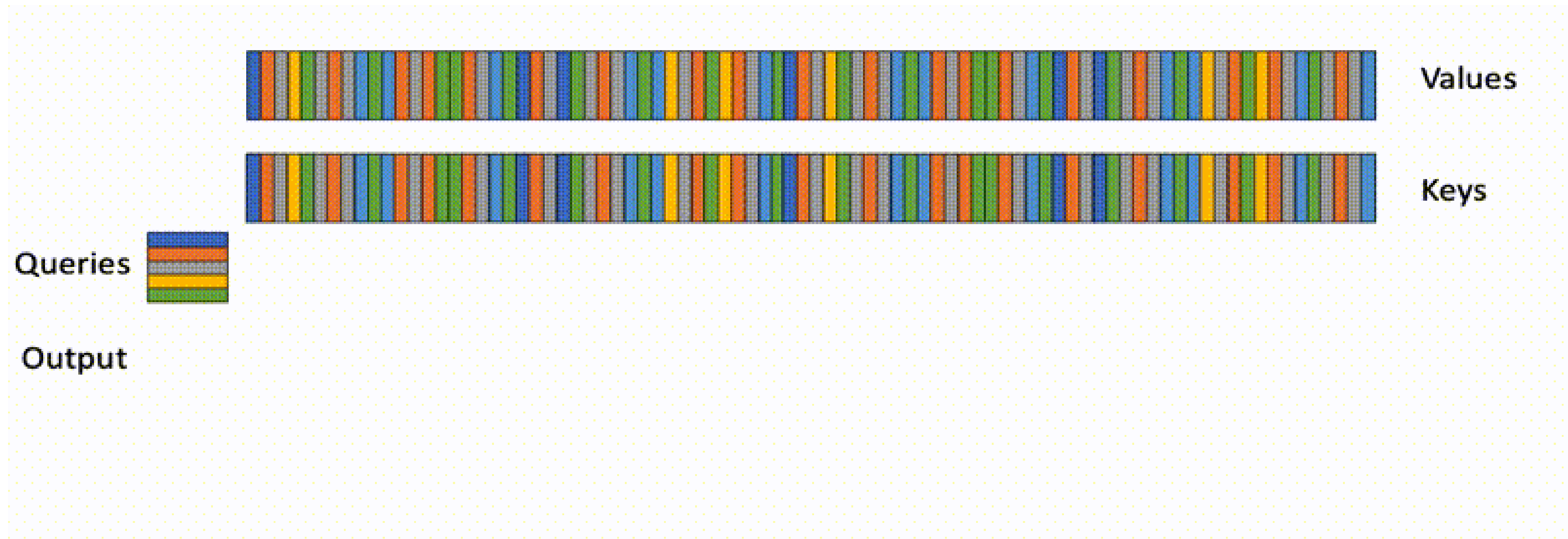
- Yes, compute different queries using different thread blocks/warps



Decoding phase:

- No, there is a single query in the decoding phase

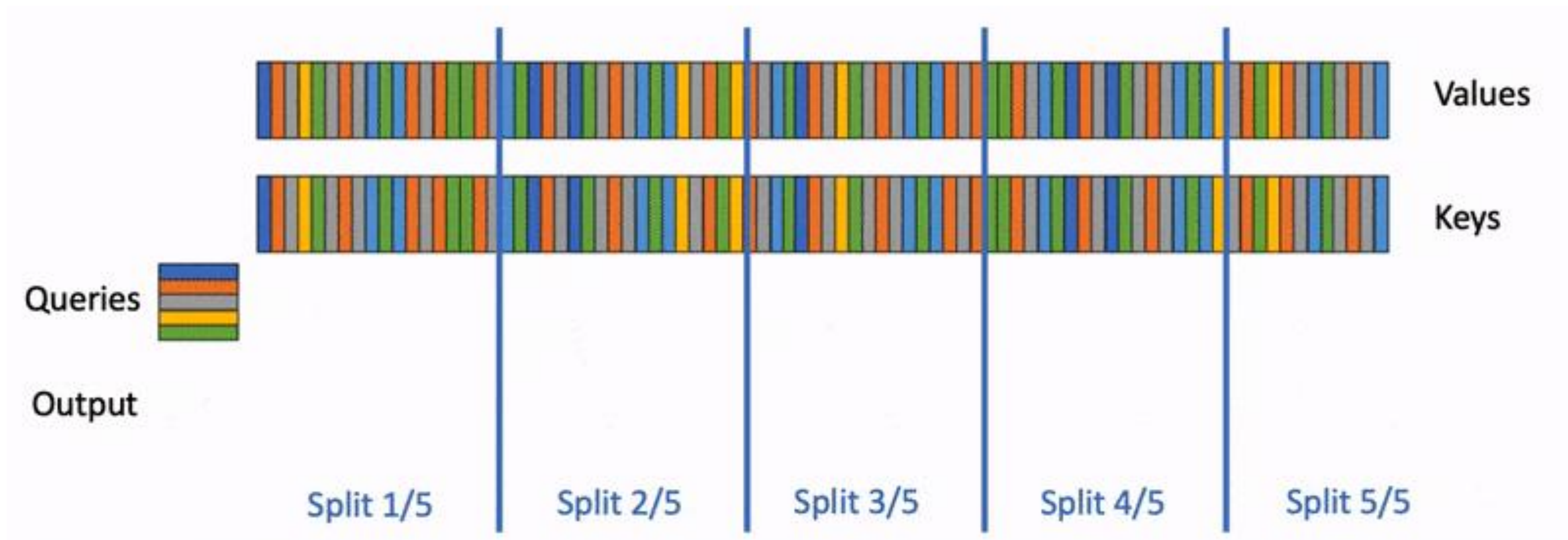
FlashAttention Processes K/V Sequentially



Inefficient for requests with long context (many keys/values)

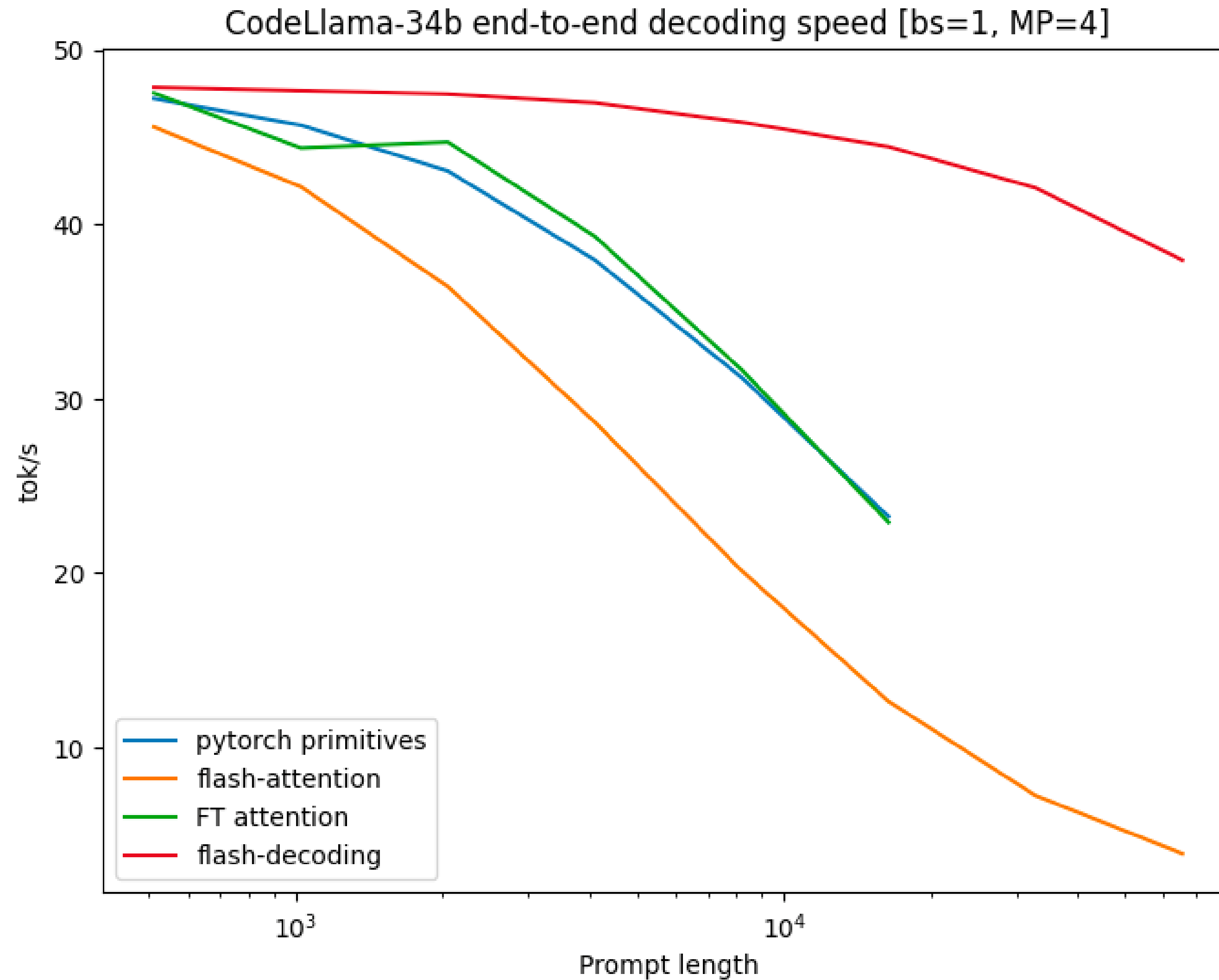
Flash-Decoding Parallelizes Across Keys/Values

1. Split keys/values into small chunks
2. Compute attention with these splits using FlashAttention
3. Reduce overall all splits



Key insight: attention is associative and commutative

Flash-Decoding is up to 8x faster than prior work



Outline: Attention Optimizations

Part 1: LLM Training

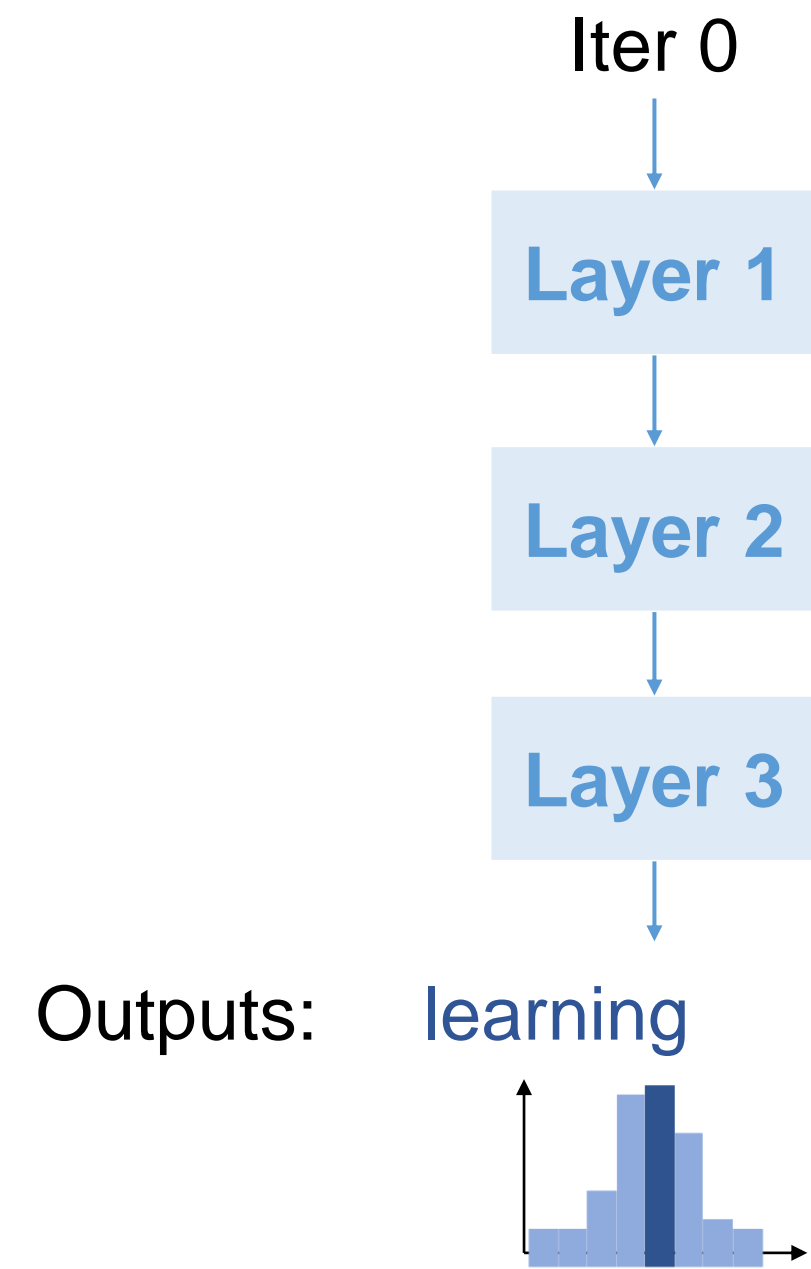
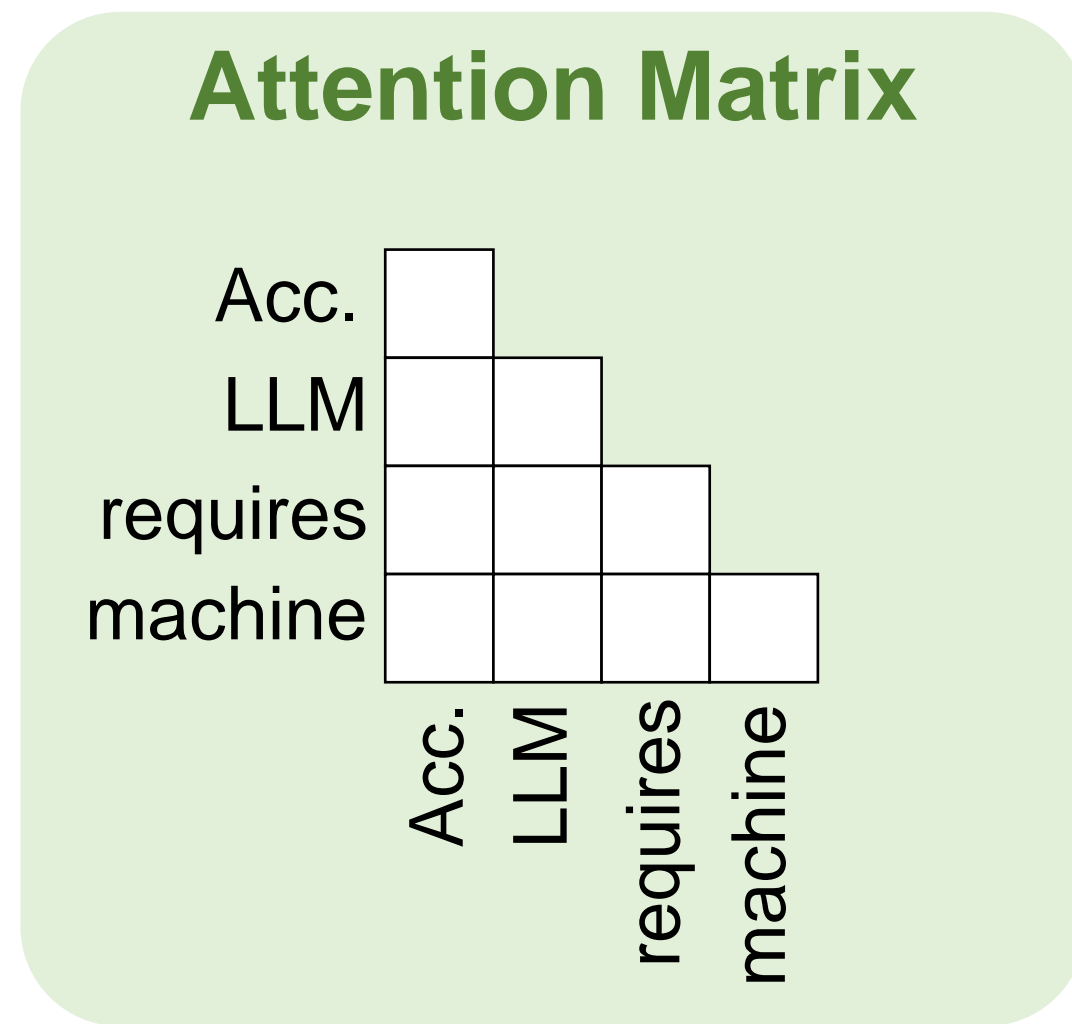
- FlashAttention

Part 2: LLM Inference (Auto-regressive Decoding)

- Flash-Decoding
- **PagedAttention**

KV Cache Dynamically Grows and Shrinks

[Accelerating LLM requires machine]



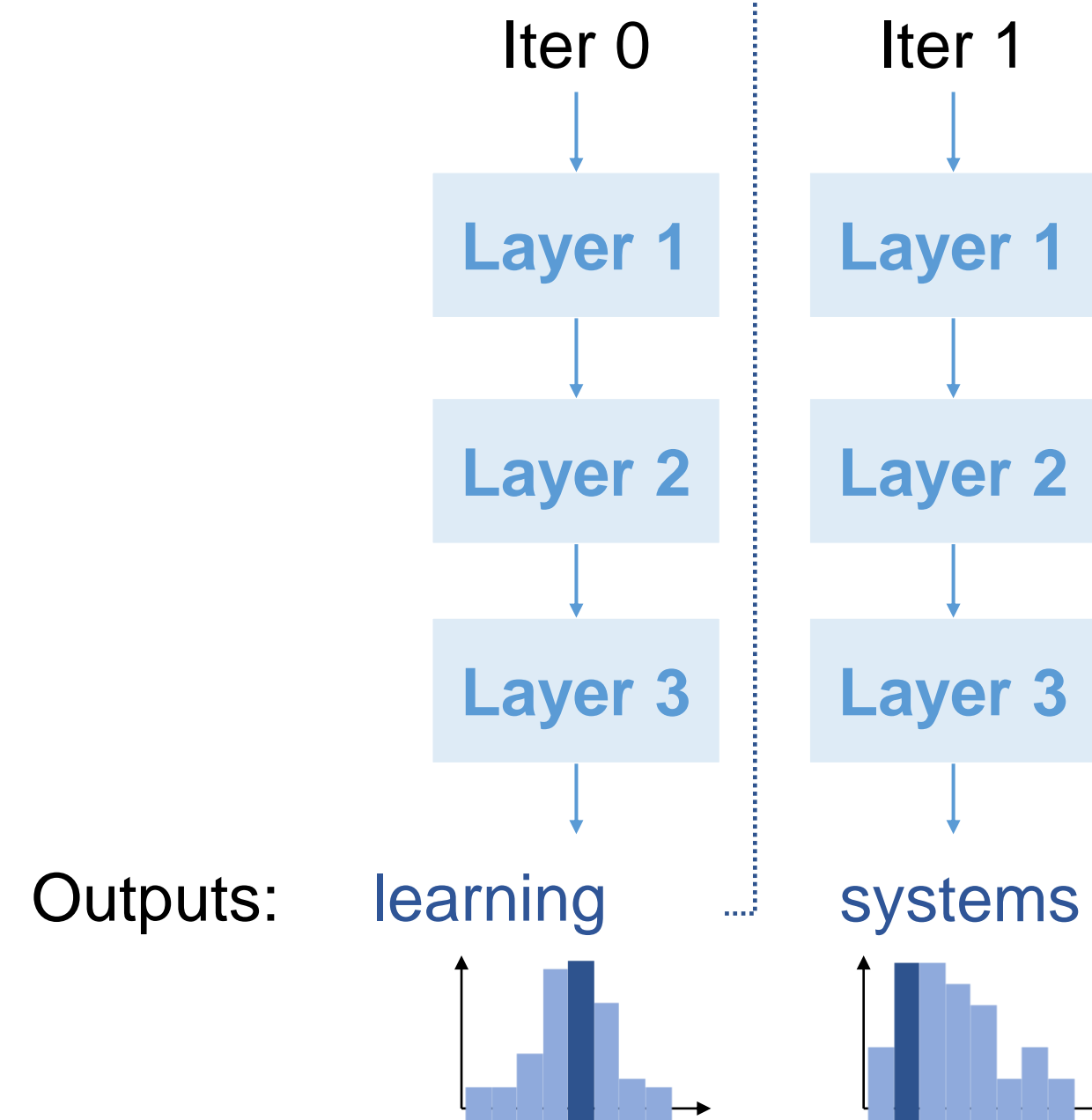
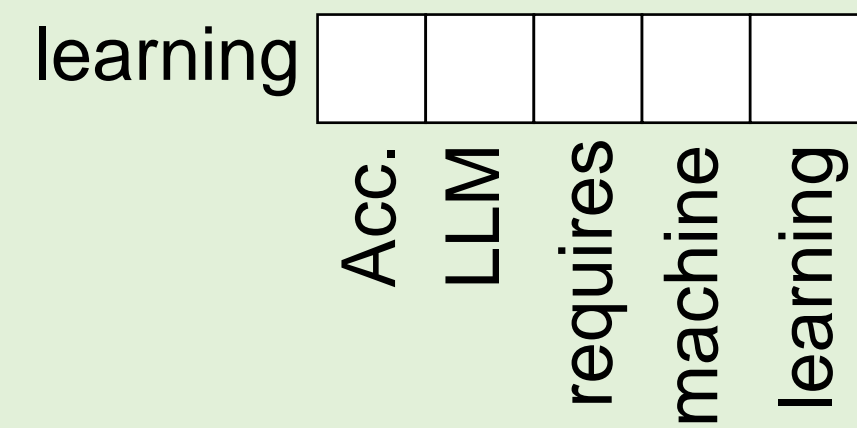
KV Cache



KV Cache Dynamically Grows and Shrinks

[Accelerating LLM requires machine] → learning

Attention Matrix



KV Cache

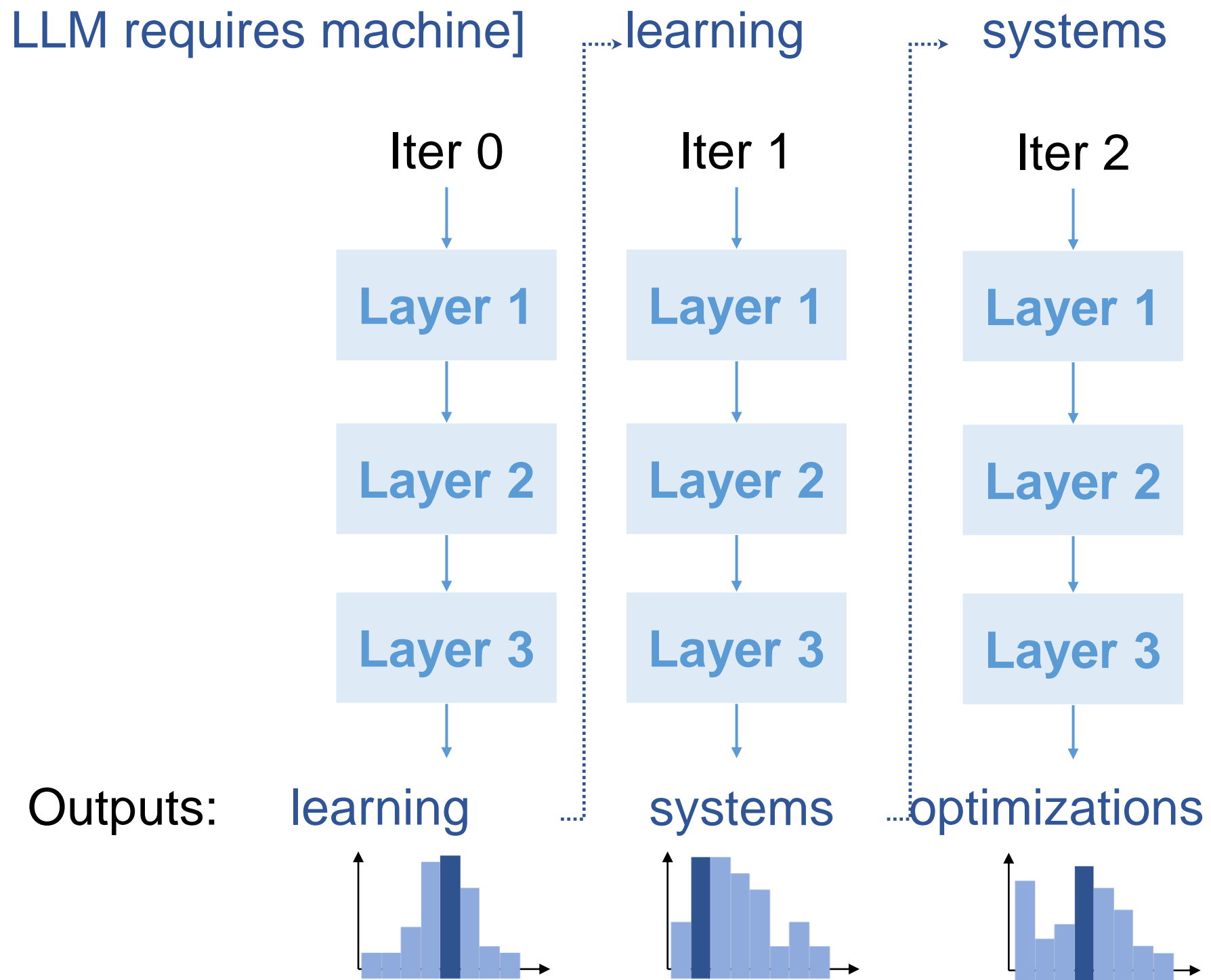


KV Cache Dynamically Grows and Shrinks

[Accelerating LLM requires machine]

Attention Matrix

systems						
	Acc.	LLM	requires	machine	learning	systems

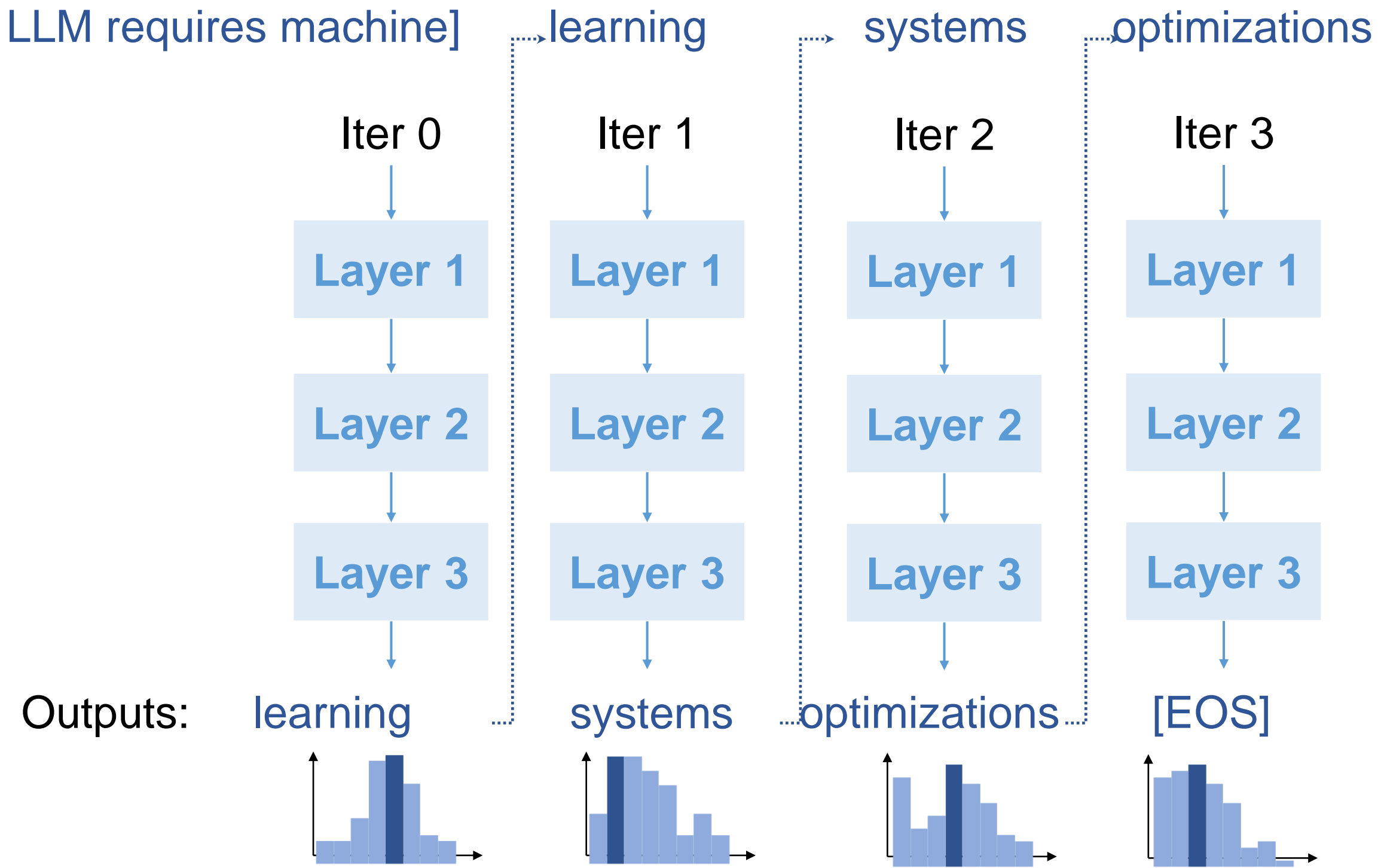
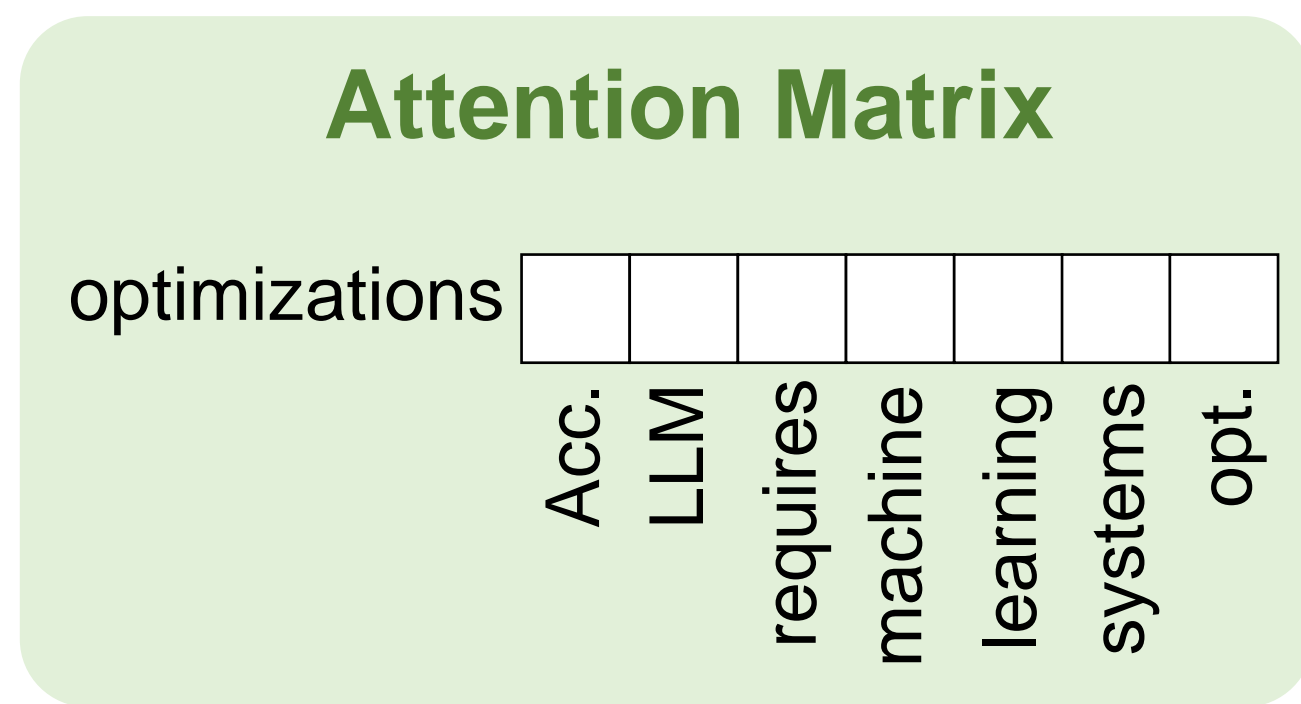


KV Cache

Accelerating	LLM	requires	machine	learning	systems
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KV Cache Dynamically Grows and Shrinks

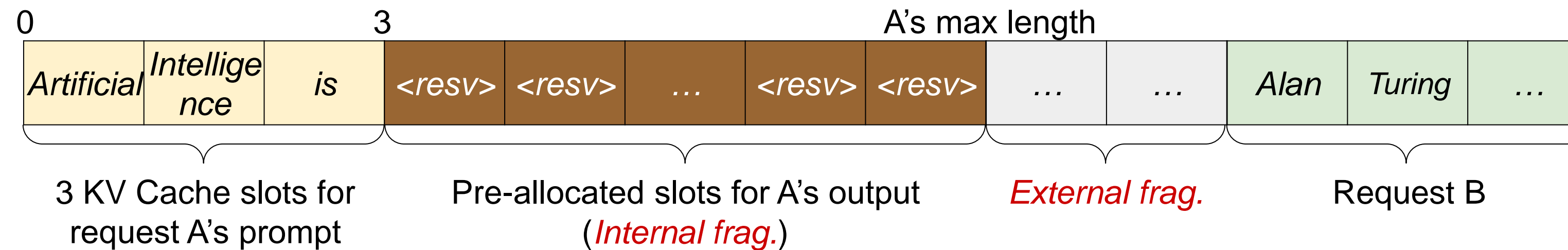
[Accelerating LLM requires machine]



KV Cache



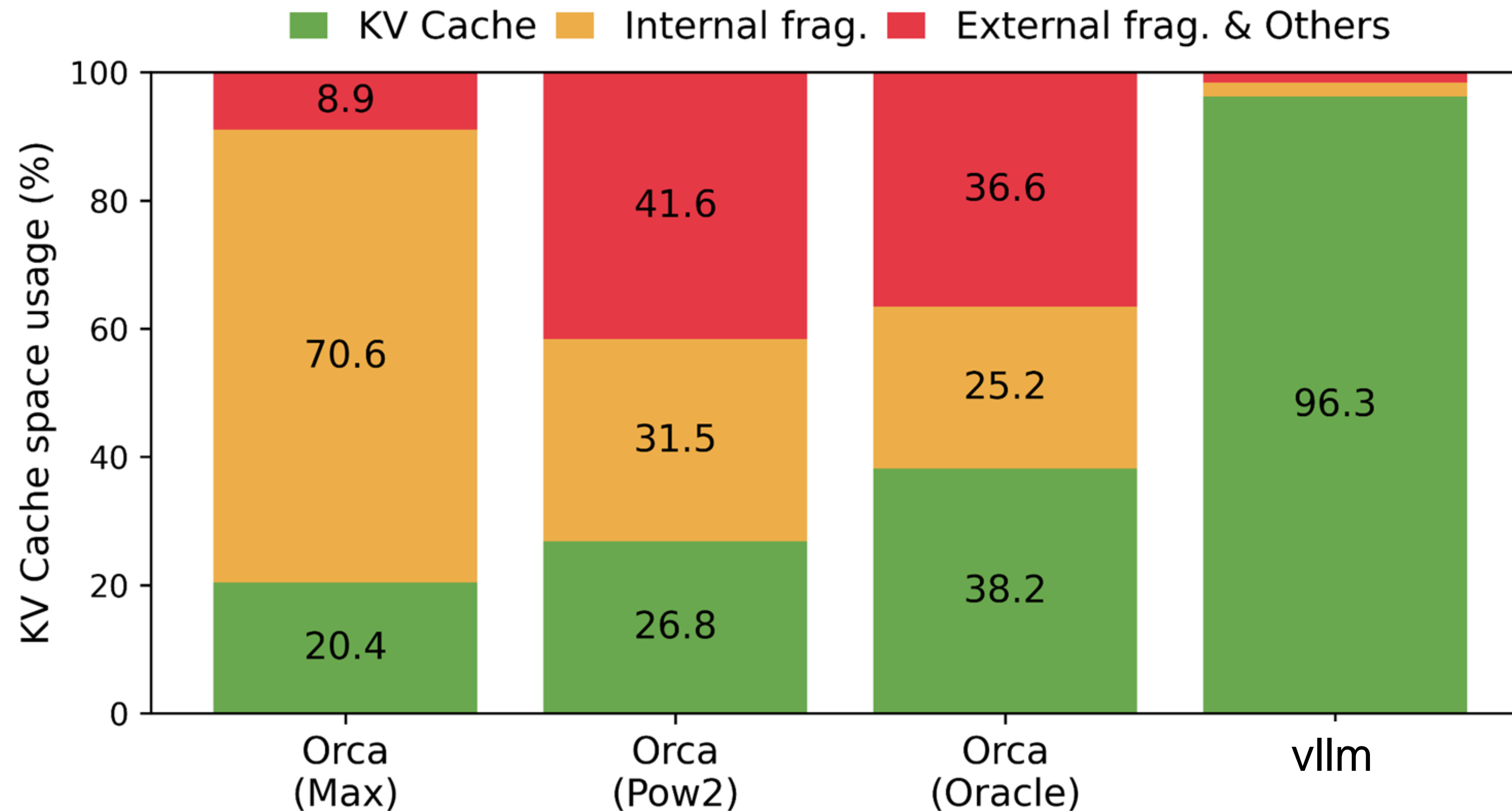
Static KV Cache Management Wastes Memory



- **Pre-allocates contiguous** space of memory to the request's maximum length
- Memory fragmentation
 - **Internal fragmentation** due to unknown output length
 - **External fragmentation** due to non-uniform per-request max lengths

Significant Memory Waste in KV Cache

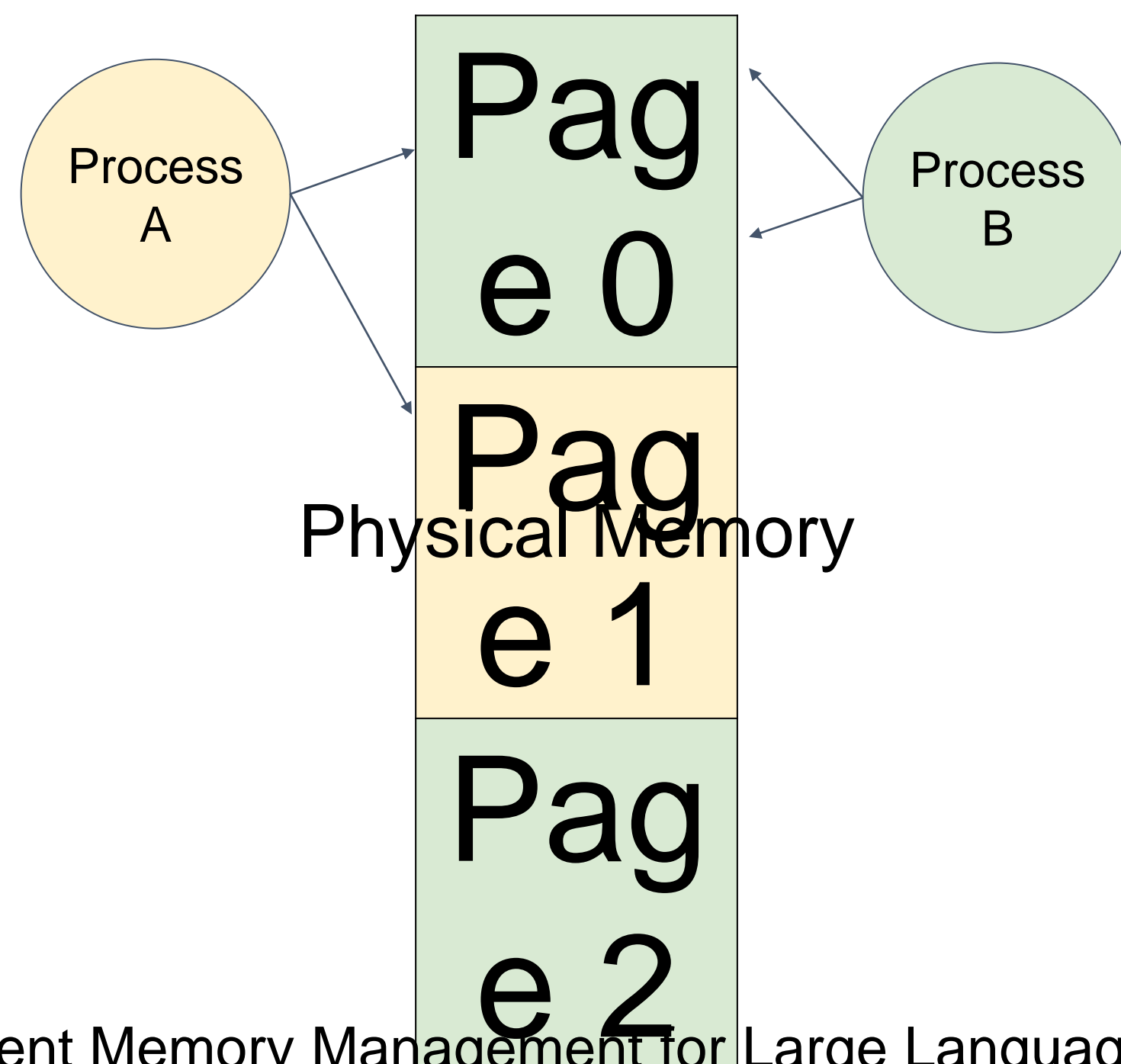
- Only 20-40% of KV cache is utilized to store actual token states



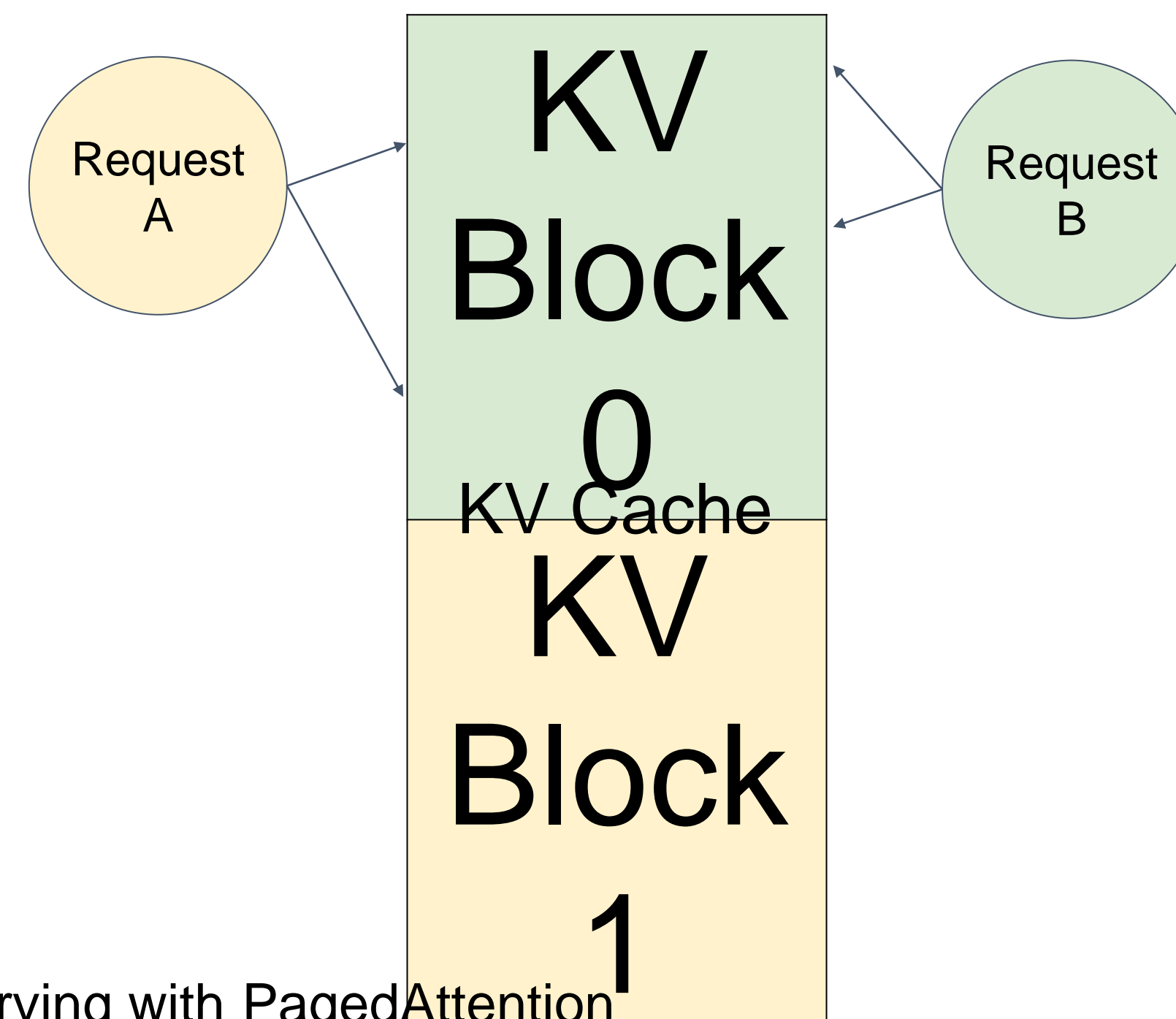
PagedAttention

- Application-level memory paging and virtualization for KV cache

Memory management in OS

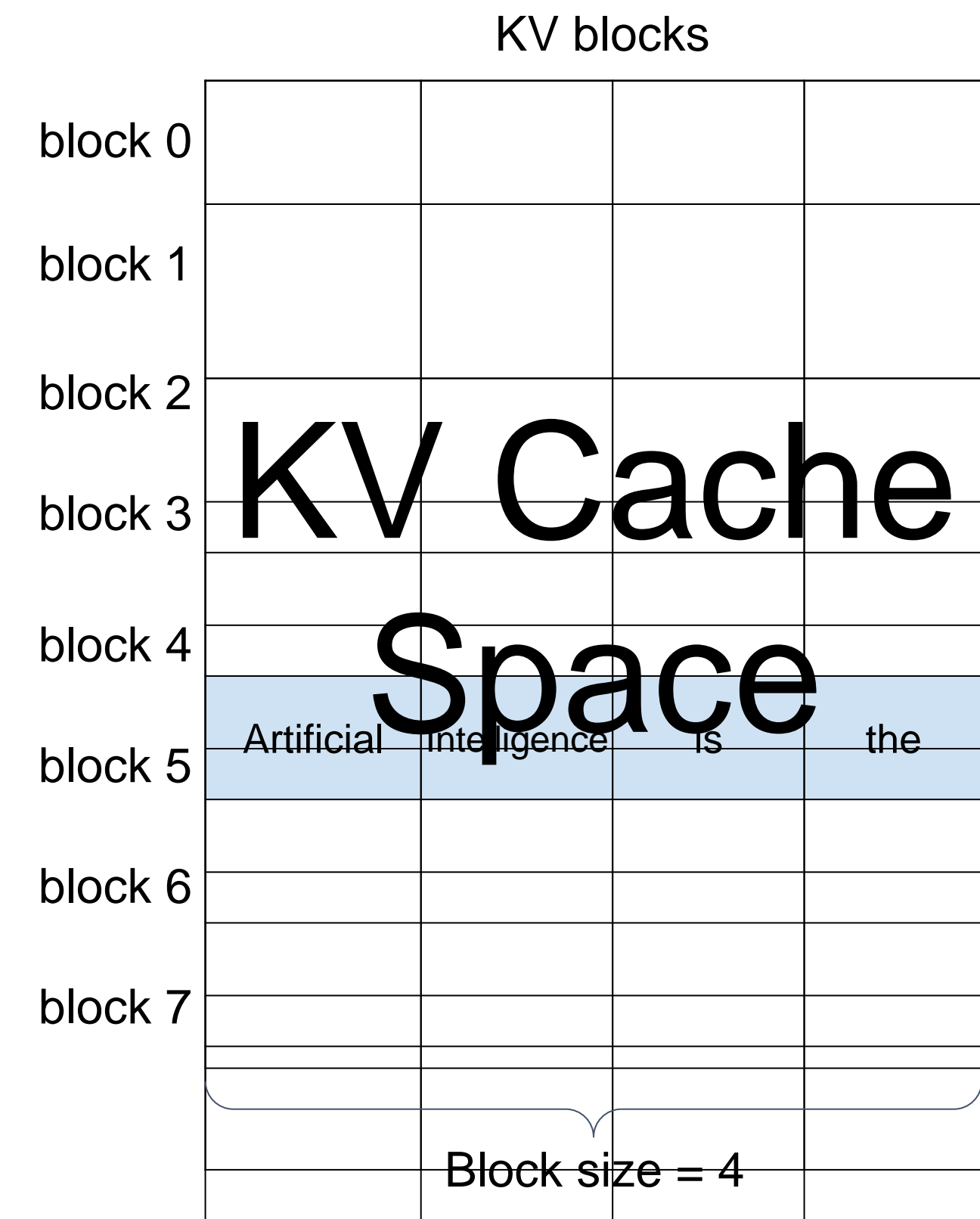


PagedAttention



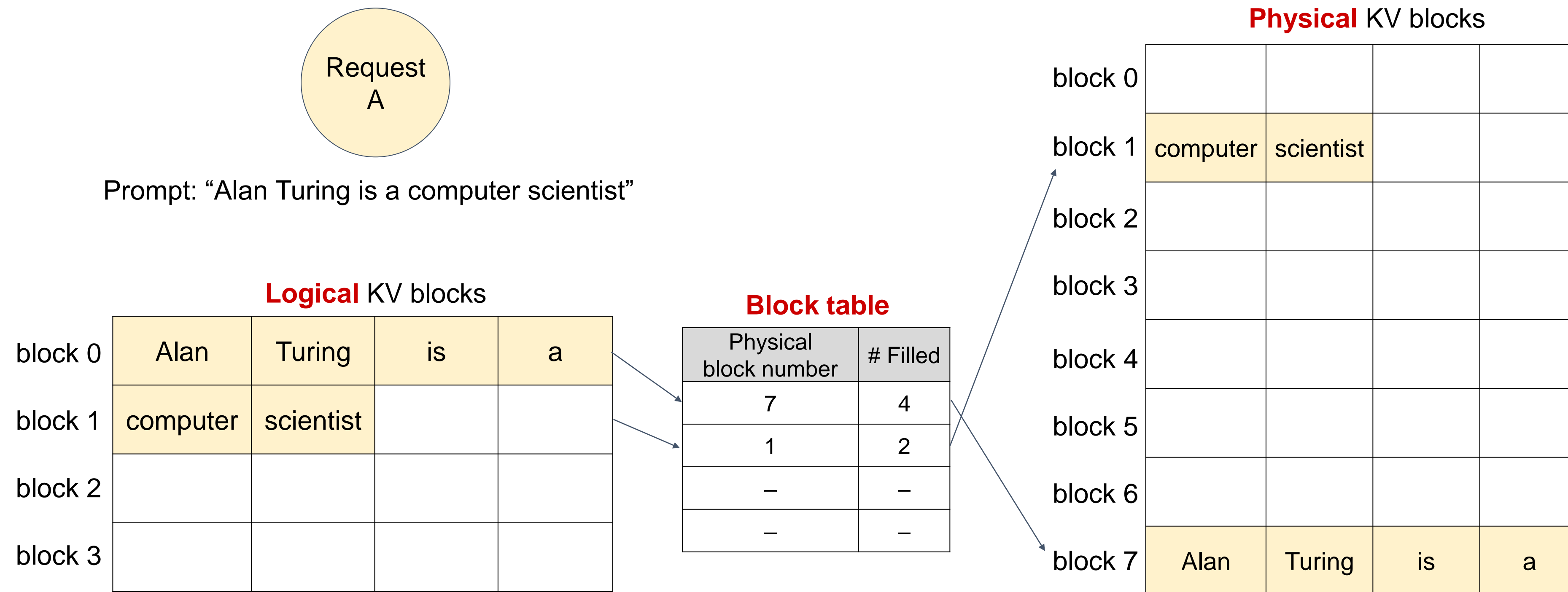
Paging KV Cache Space into KV Blocks*

- KV block is a **fixed-size** contiguous chunk of memory that stores KV states from **left to right**



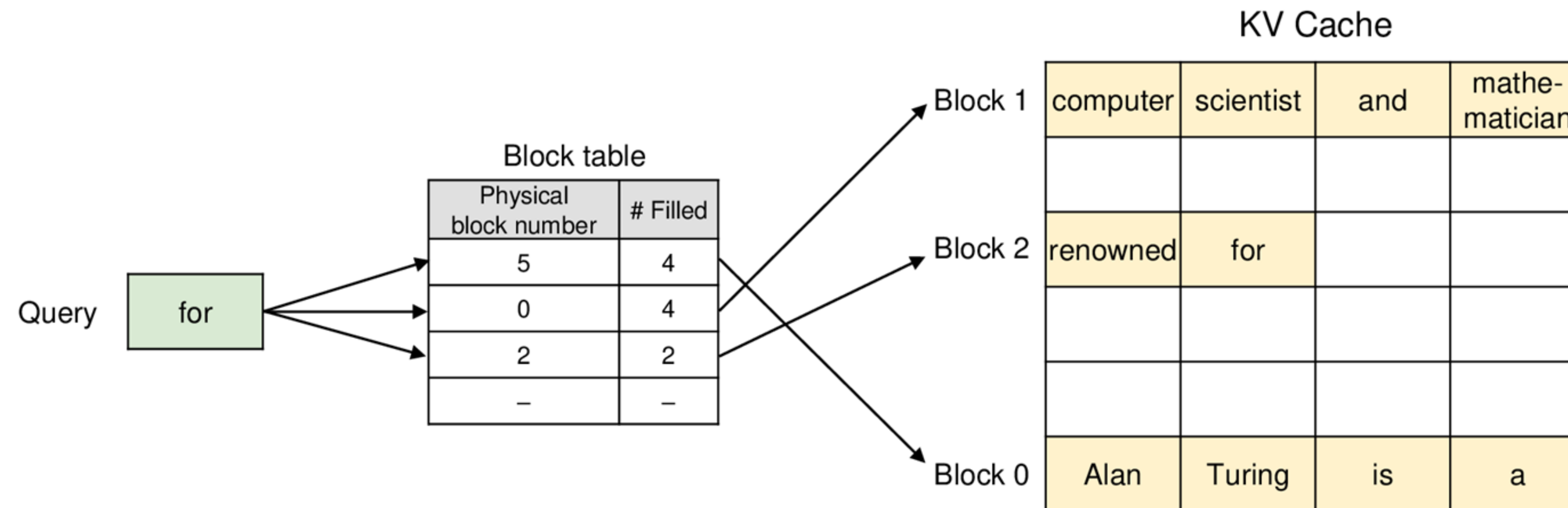
* The term ``block'' is overloaded in PagedAttention

Virtualizing KV Cache



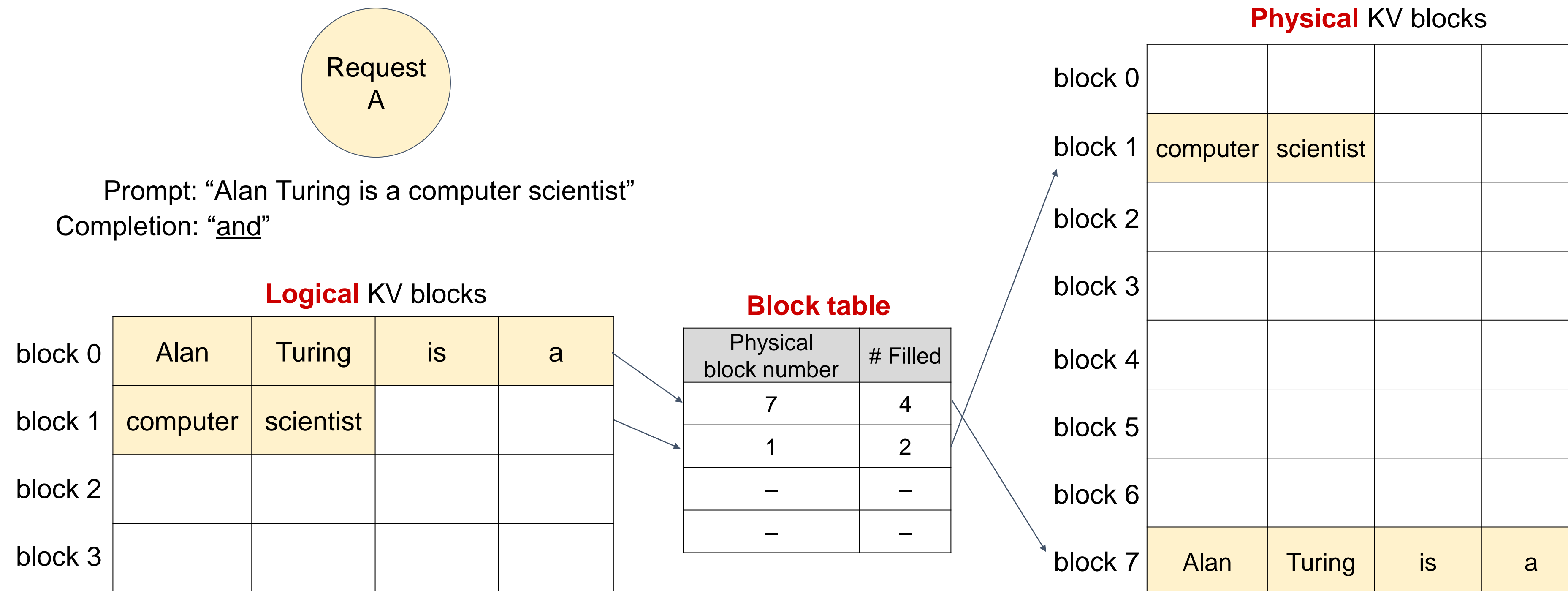
Attention with Virtualized KV Cache

1. Fetch non-contiguous KV blocks using the block table
2. Apply attention on the fly

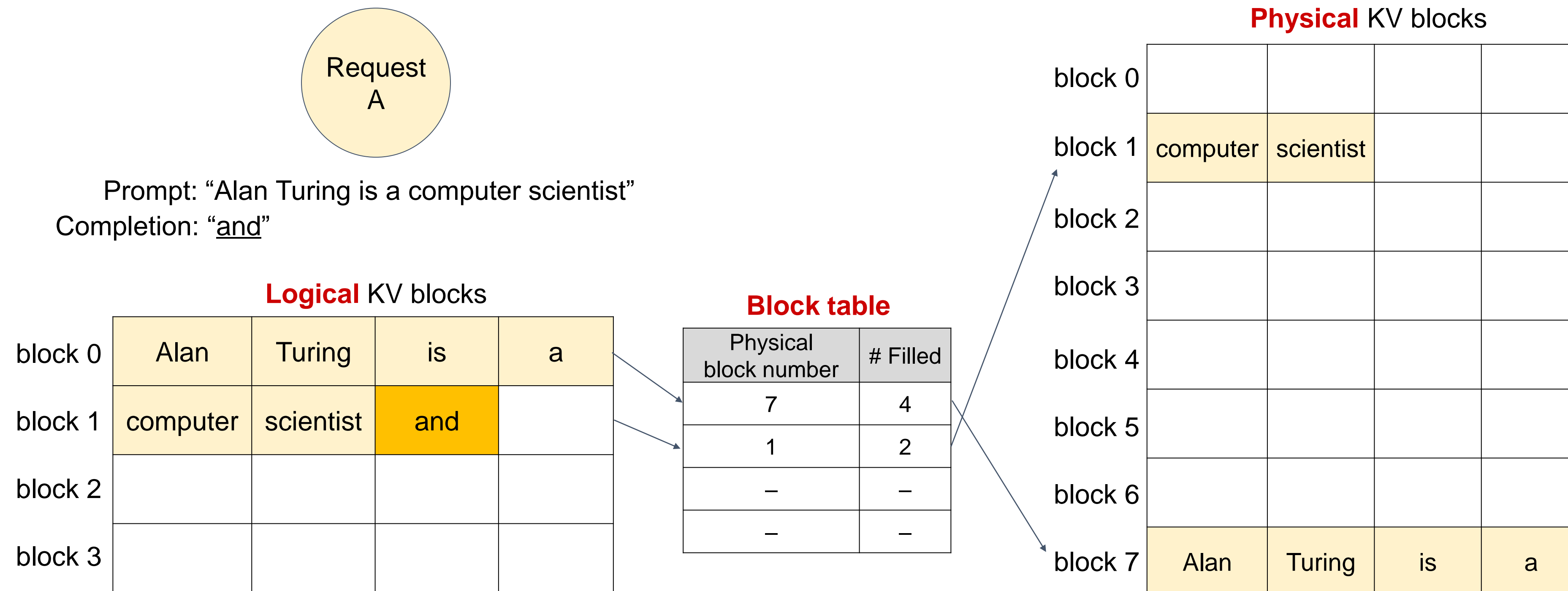


Key insight: attention is associative and commutative

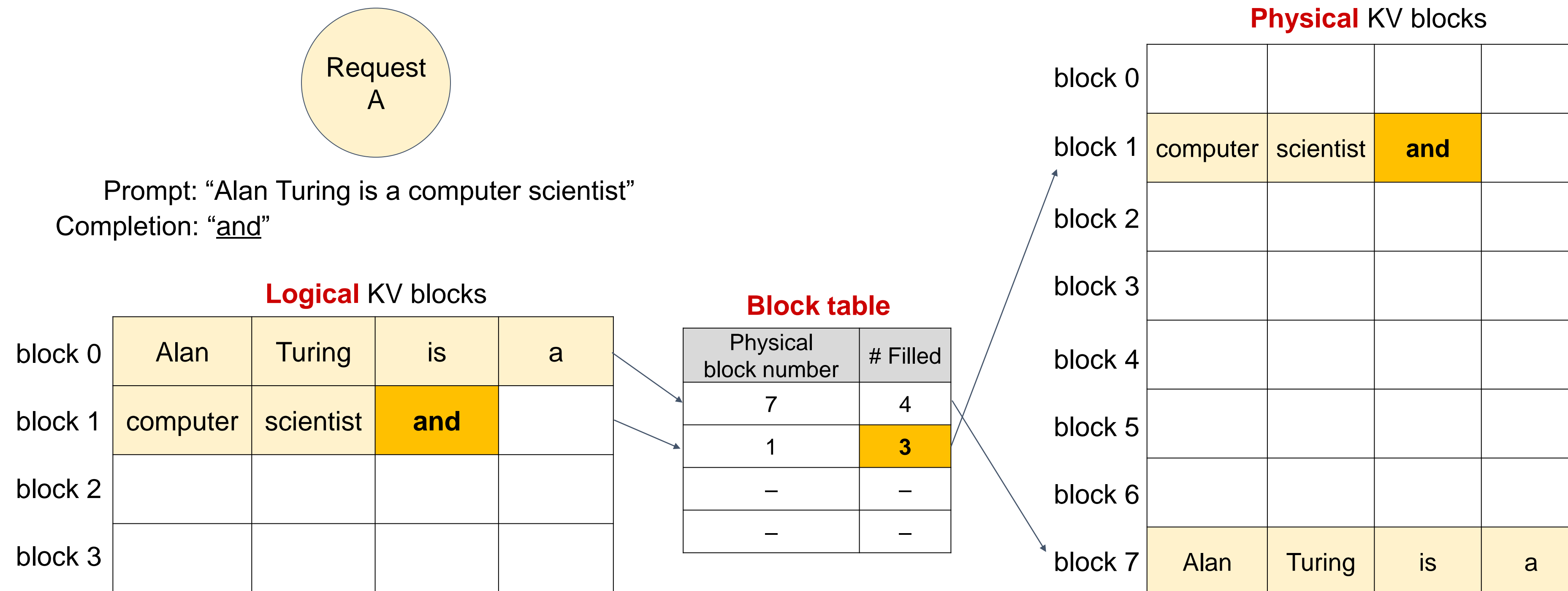
Memory Management with PagedAttention



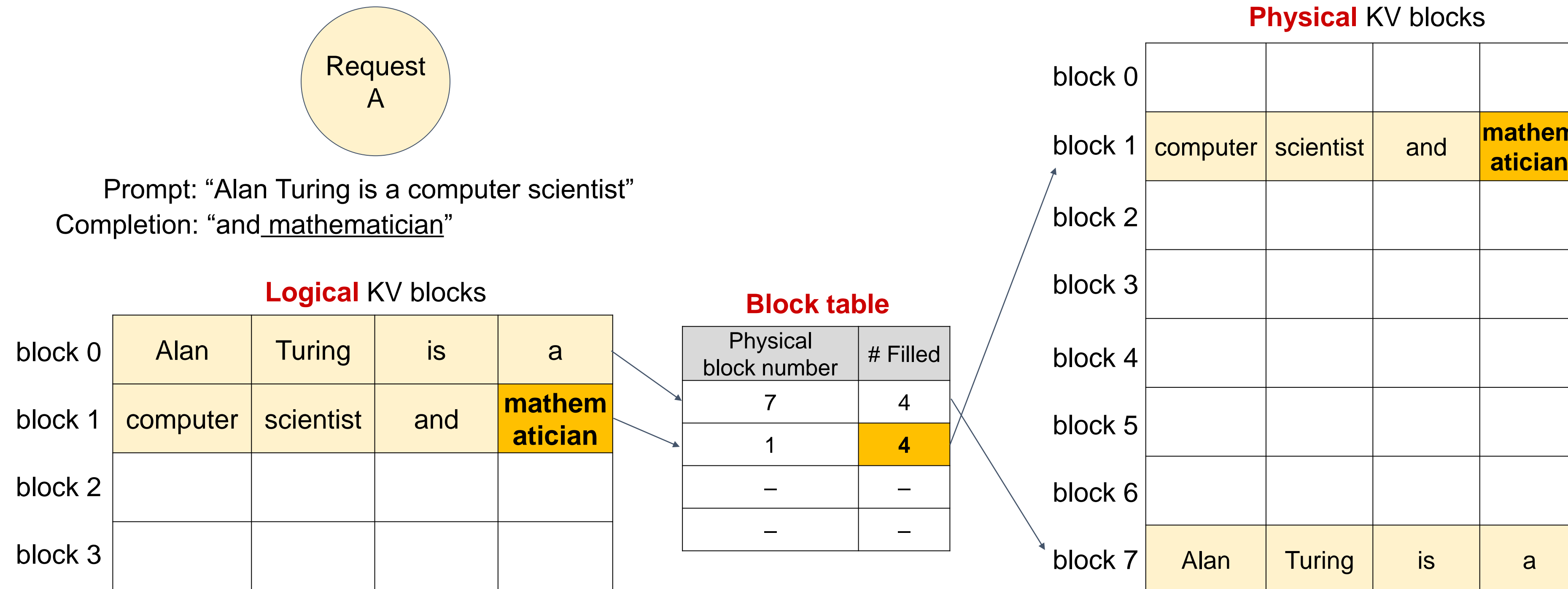
Memory Management with PagedAttention



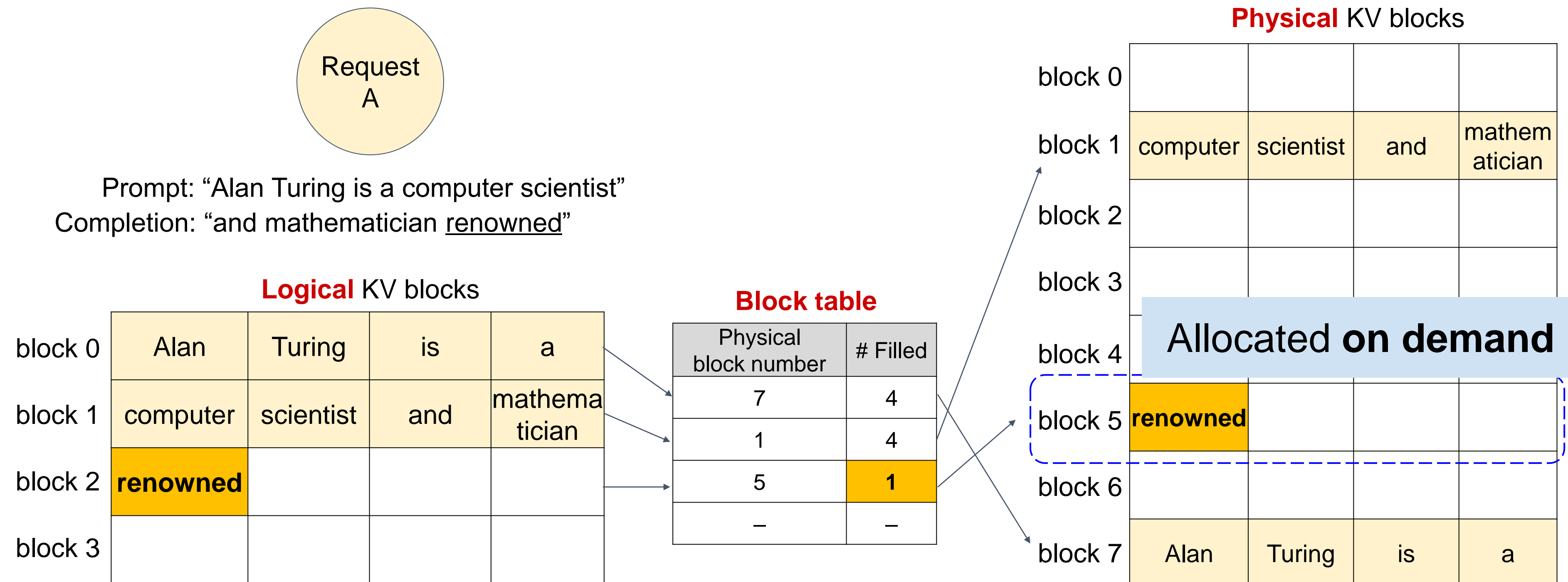
Memory Management with PagedAttention



Memory Management with PagedAttention



Memory Management with PagedAttention



Memory Efficiency of PagedAttention

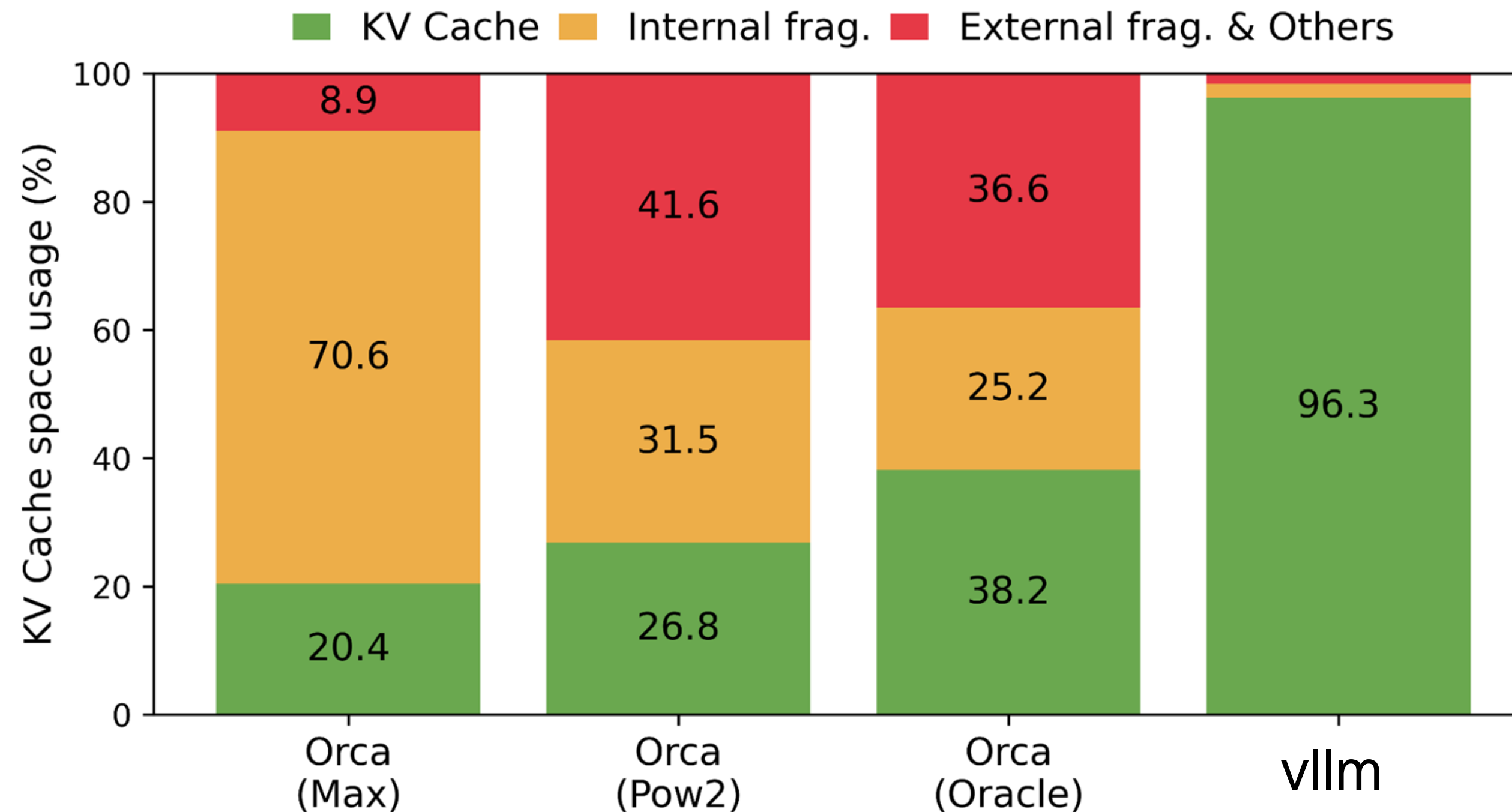
Minimal internal fragmentation

- Only happens at the last block of a sequence
- # wasted tokens / seq < block size

No external fragmentation

Alan	Turing	is	a
computer	scientist	and	mathemati cian
renowned			

Internal
fragmentation



A few Important Problems (will be HW3)

- How to estimate the number of parameters of an LLM?
 - Embedding: position + word
 - Transformers layers:
 - attention W_q, W_k, W_v
 - MLP: up project, down project
 - Layernorm parameters
- How to estimate the flops needed to train an LLM?
- How to estimate the memory needed to train a transformer?